

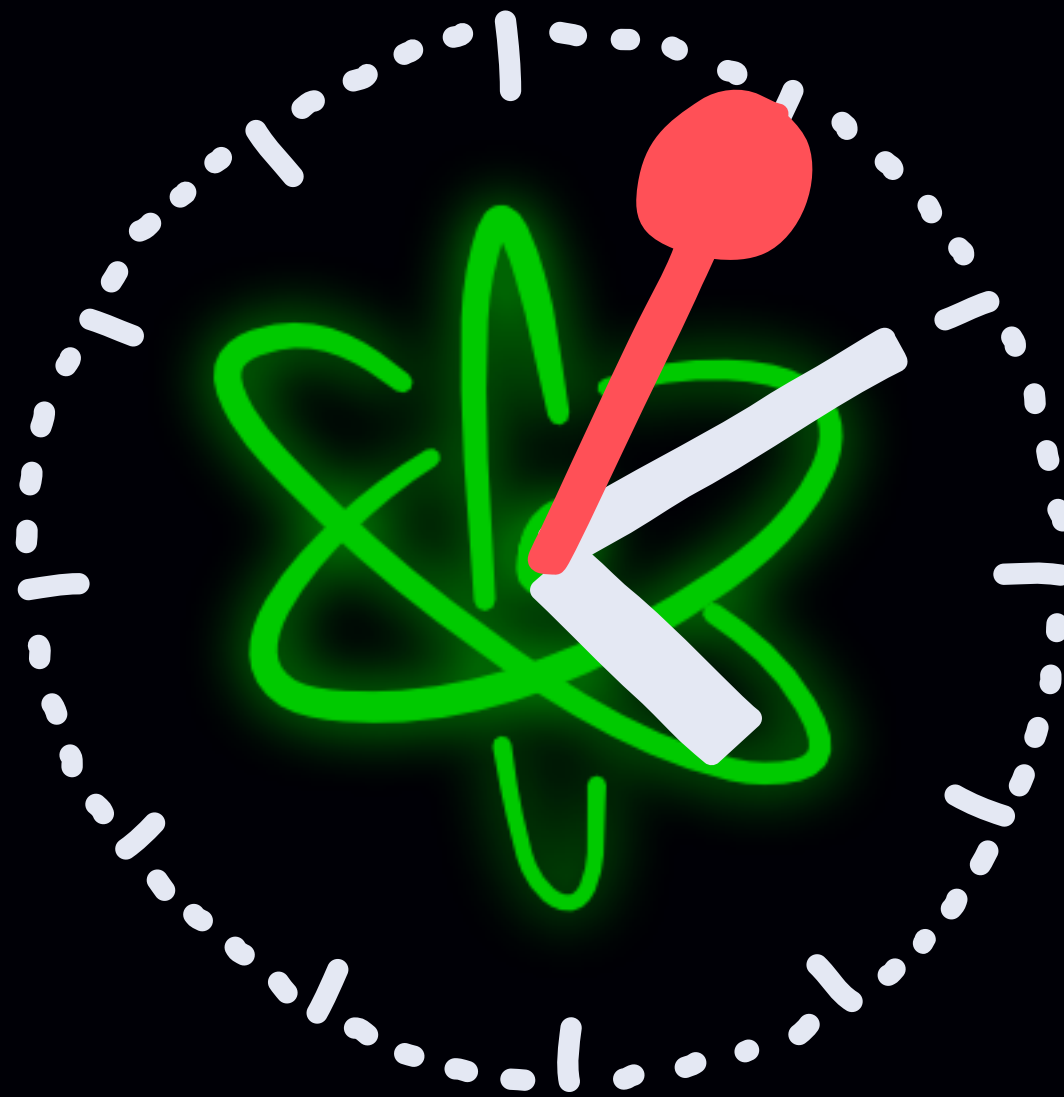
Bipartite time–energy uncertainty relation for quantum metrology with noise

Philippe Faist, Mischa P Woods,
Victor V Albert, Joseph M Renes,
Jens Eisert, John Preskill

*Free Univ. Berlin, Caltech, ETH Zurich, NIST,
Univ. Maryland, AWS*

unitary time evolution
of $|\psi\rangle$ according to H

measurement reveals
information about
elapsed time

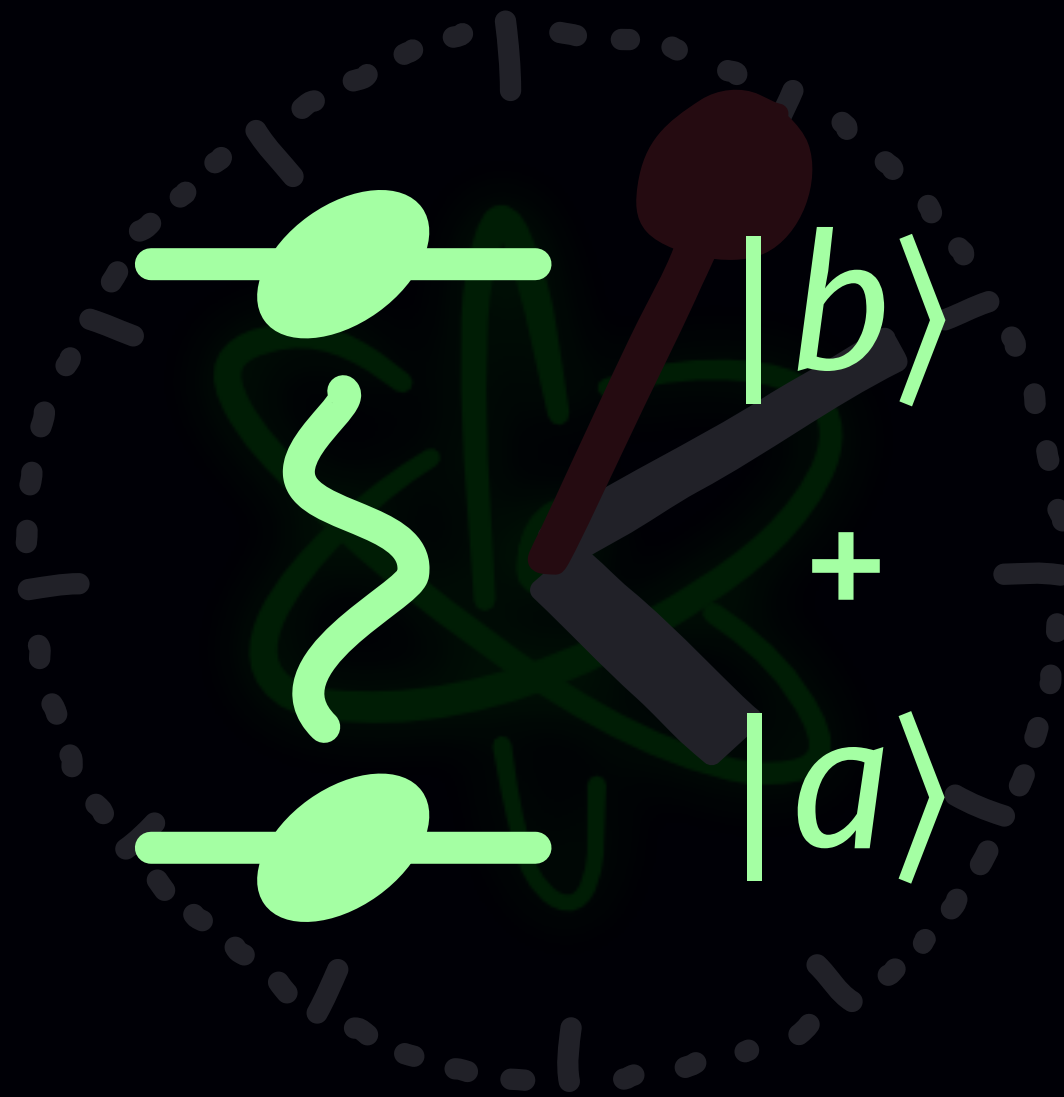


SI definition
of the second
Woods+ AHP 2019
Bartlett+ RMP 2006

...

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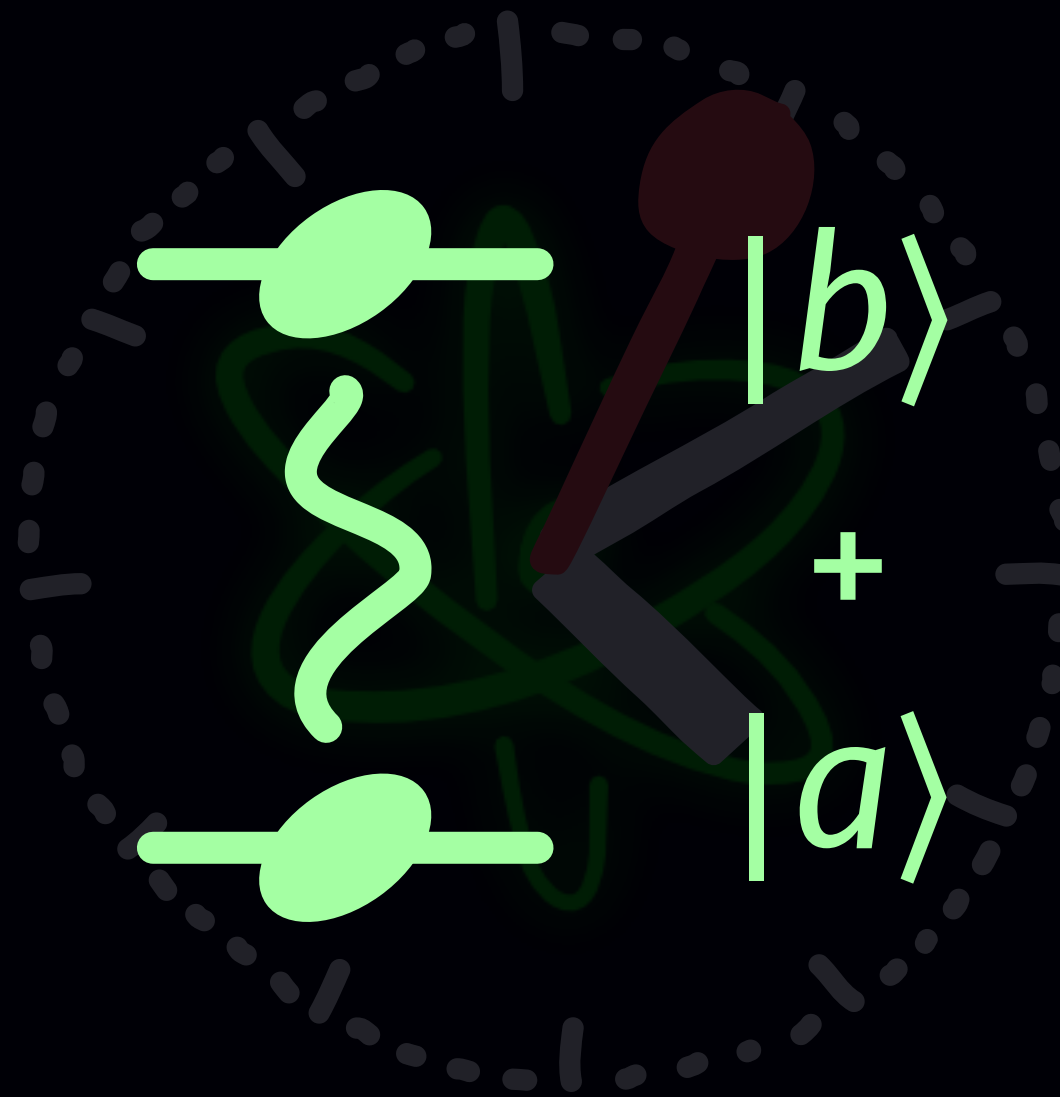


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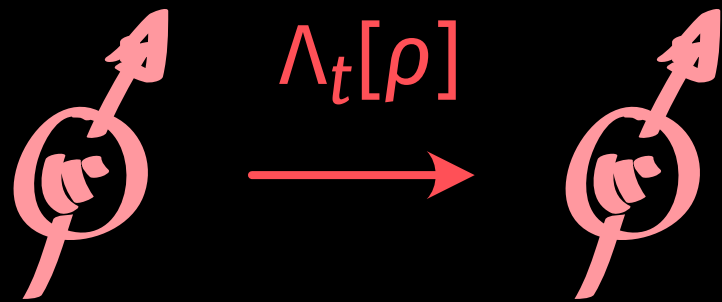
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SI definition
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...

How does noise affect the
sensitivity of the clock?

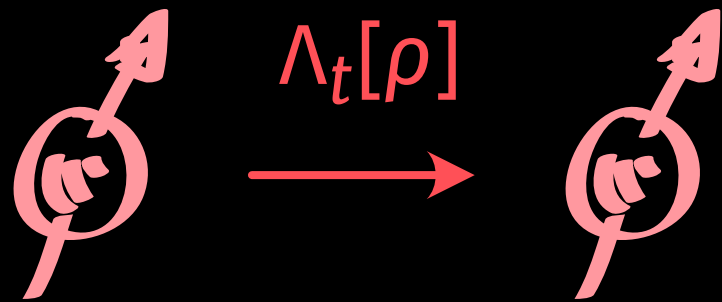


Achieve same sensitivity scaling as
without noise (Heisenberg scaling)



The signal Hamiltonian is not parallel to
the noise (Hamiltonian not in Lindblad span)

Demkowicz–Dobrzański+ N. Comm. 2011; Escher+ N. Phys 2011;
Kessler+ / Arrad+ / Dür+ PRL 2014;
Zhou+ N. Comm. 2018; Layden+ PRL 2019; ...



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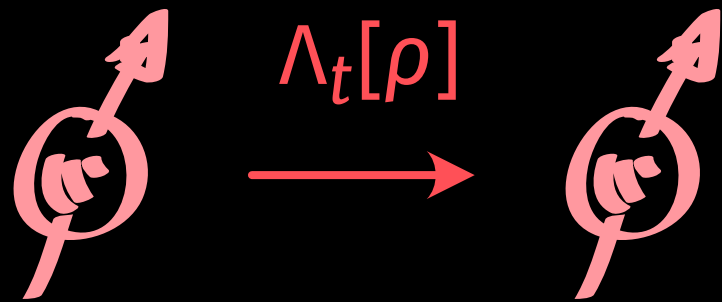
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use
time-covariant
error-correcting
code

Hayden *et al.*, 1709.04471





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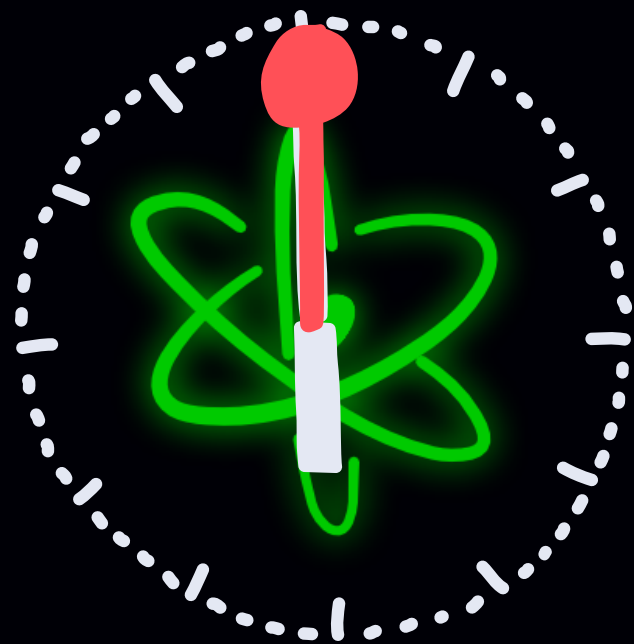
use approximate
time-covariant
error-correcting
code



Hayden *et al.*, 1709.04471

PhF+ PRX 2020; Woods & Alhambra *Quantum* 2020;

Kubica+ 2004.11893; Zhou+ 2005.11918; Yang+ 2007.09154



$t = 0$



$$t = t_0$$



$t = t_0$



How much
sensitivity is left?

? • Uncertainty relation for sensitivity: $\Delta t \Delta E \geq \hbar$
noisy clock w.r.t. time $\leftrightarrow$ environment w.r.t. energy

$\hookrightarrow$ Expression for sensitivity loss



Uncertainty
relation for
sensitivity:

noisy clock
w.r.t. time

$<>$

environment
w.r.t. energy



Expression for sensitivity loss

*(methods from
semidefinite
programming)*

› alternative
sensitivity
bounds

› uncertainty
relation for any
two parameters



Uncertainty
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noisy clock
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Ø1

Necessary and sufficient
conditions for zero
sensitivity loss

› “metrological codes”



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Expression for sensitivity loss

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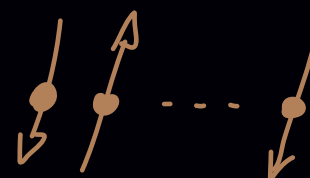
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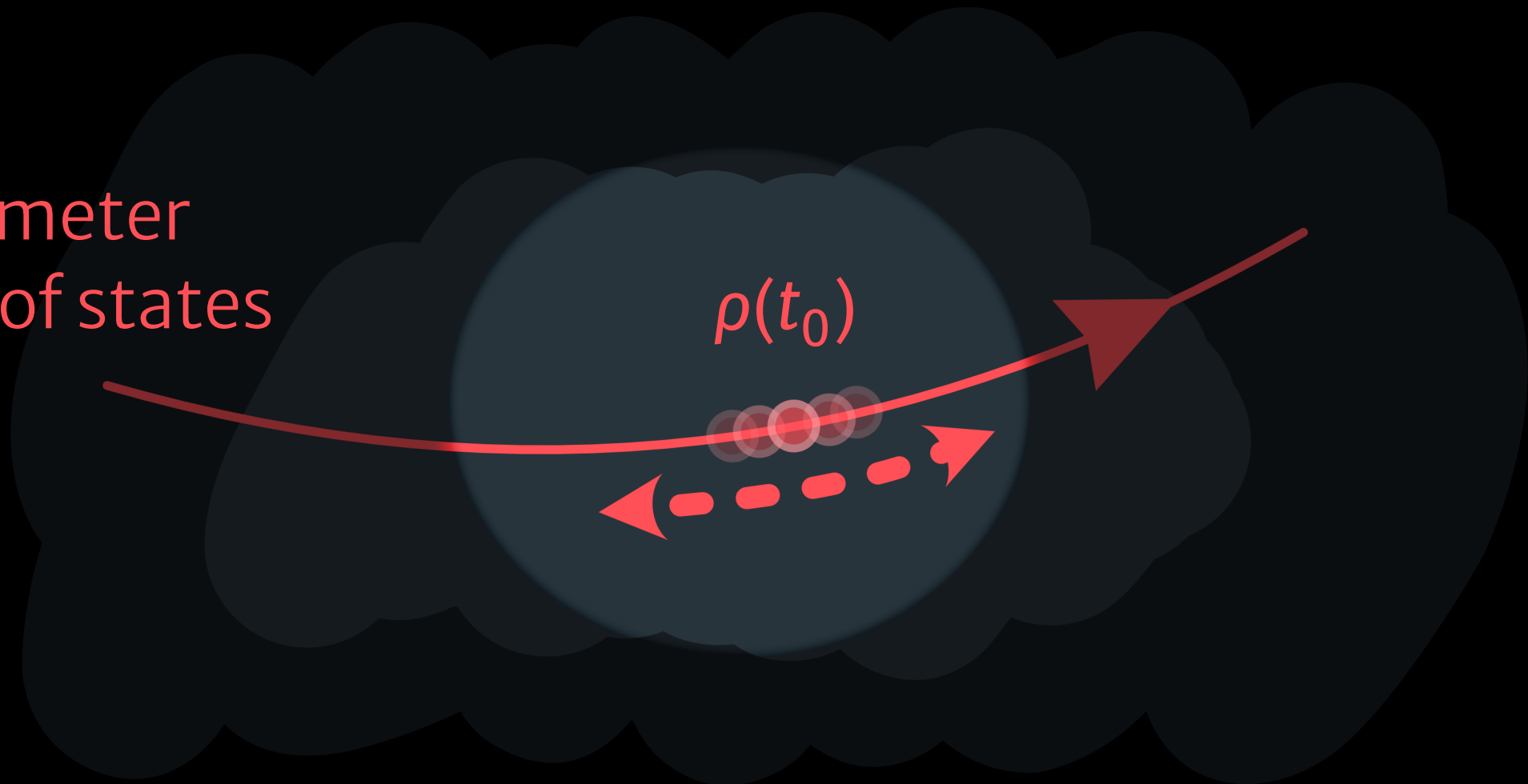
Necessary and sufficient
conditions for zero
sensitivity loss

› “metrological codes”



Example: Ising
Hamiltonian &
amplitude
damping noise

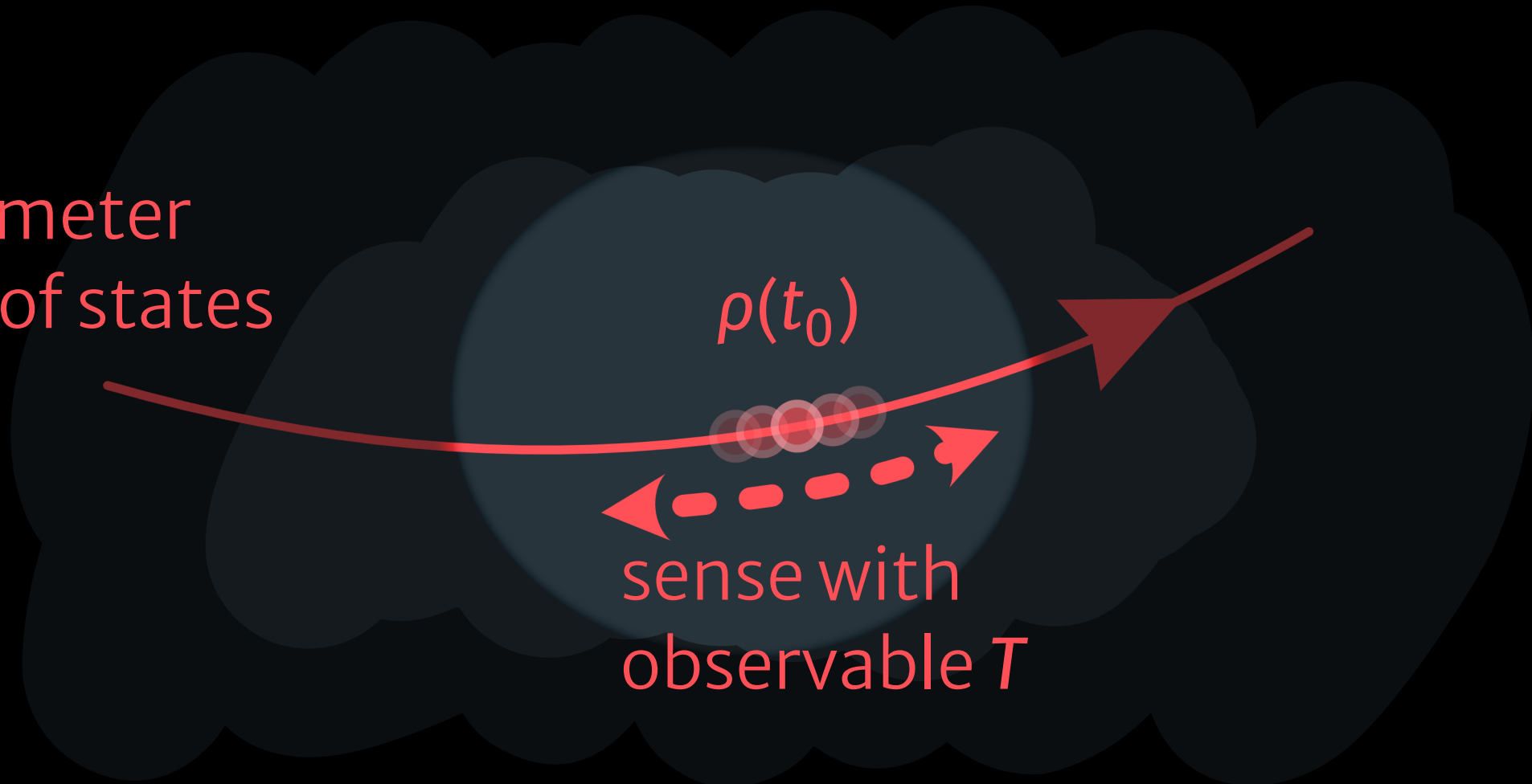
1-parameter
family of states



want: observable T with minimal variance at $\rho(t_0)$, such that:

$$\langle T \rangle_{\rho(t_0+dt)} = t_0 + dt + O(dt^2)$$

1-parameter
family of states



want: observable T with minimal variance at $\rho(t_0)$, such that:

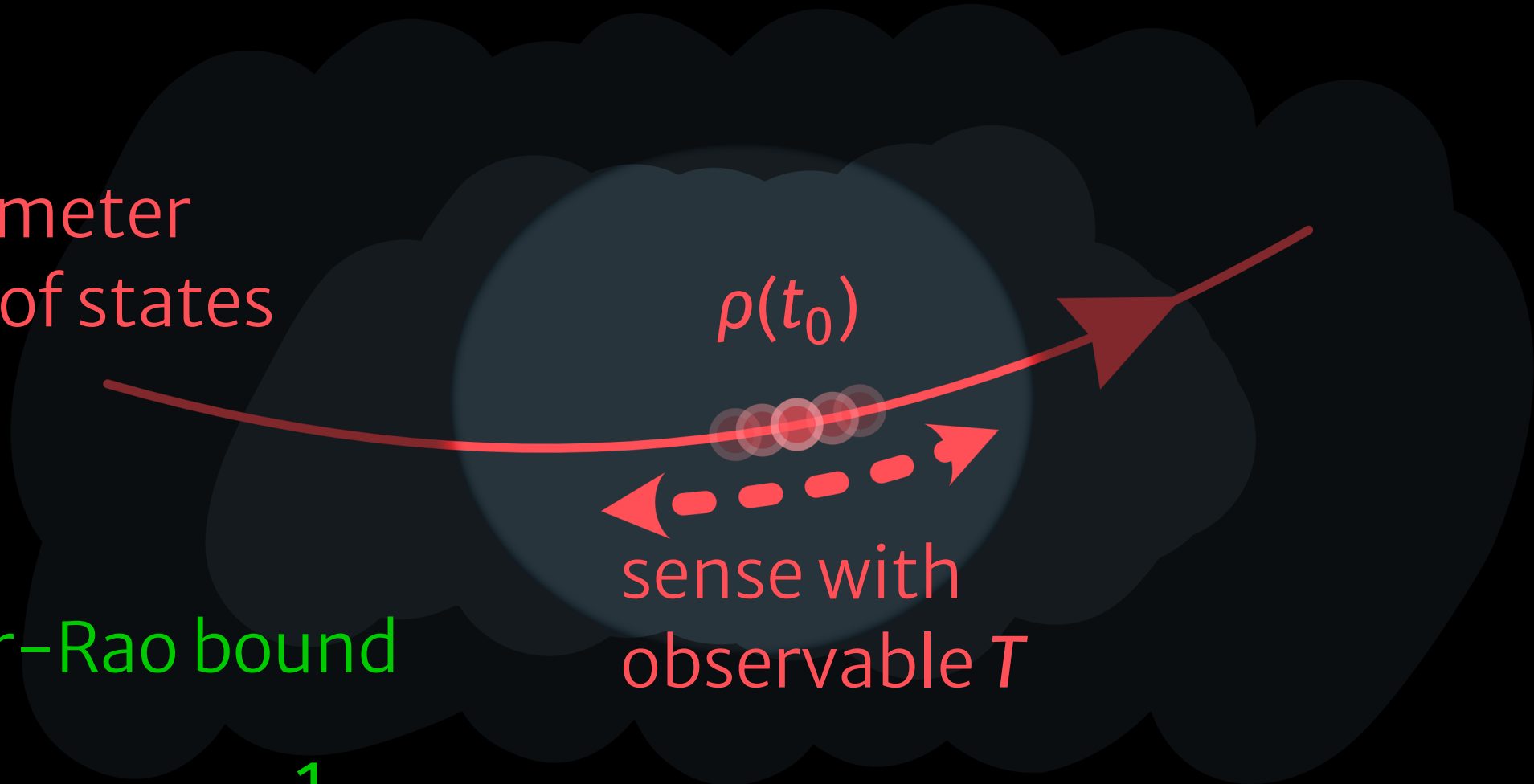
$$\langle T \rangle_{\rho(t_0+dt)} = t_0 + dt + O(dt^2)$$

1-parameter
family of states

Cramér–Rao bound

$$\langle (T - t_0)^2 \rangle \geq \frac{1}{F(\rho; \partial_t \rho)} \quad \leftarrow$$

Fisher information
(here: defined via optimal T)



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SDP Alert!

1-parameter
family of states

cf. H. Fawzi's
tutorial

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Fisher information
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$\rho(t_0)$

sense with
observable T

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$\rho(t_0)$

Cramér–Rao bound

sense with
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T is optimal
when $\{\rho, T\} \propto \partial_t \rho$

(“symmetric log. derivative”)

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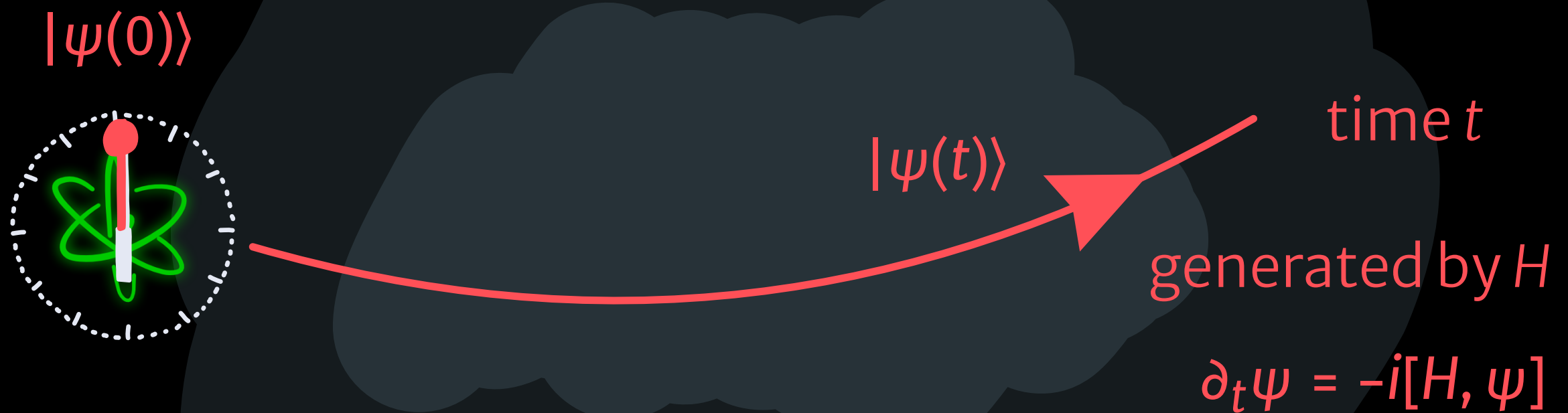
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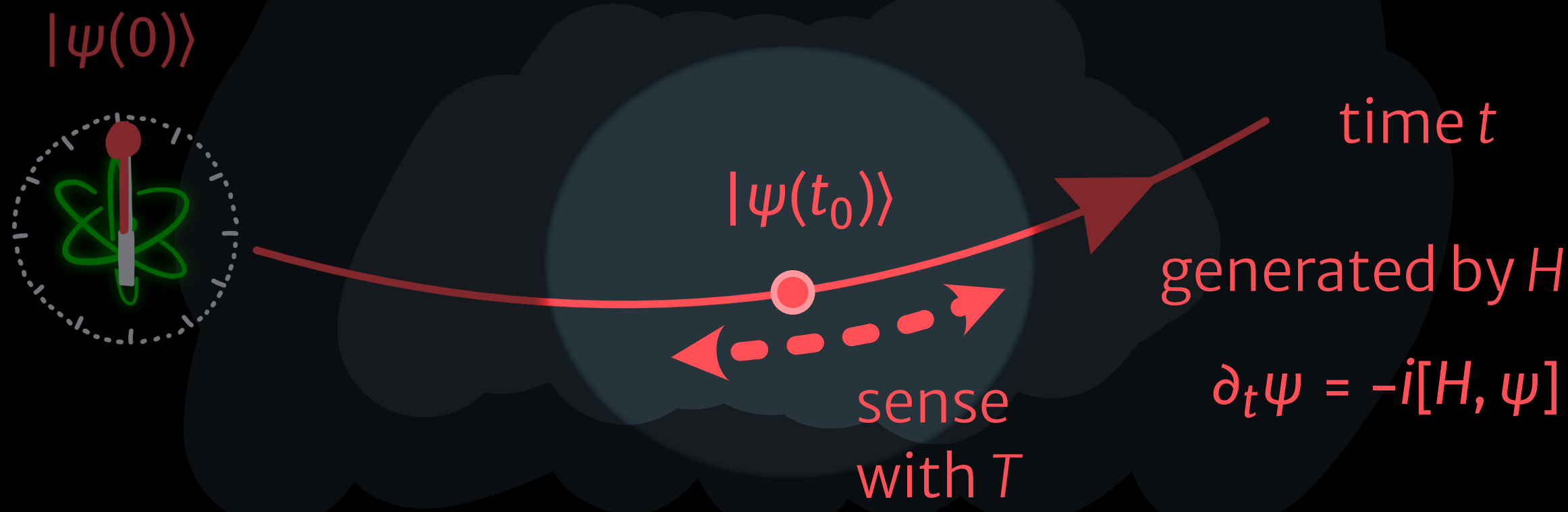
sense with
observable T

T is optimal
when $\{\rho, T\} \propto \partial_t \rho$

(“symmetric log. derivative”)

$F(\rho; \partial_t \rho)$ & T can be tricky to
determine for mixed ρ



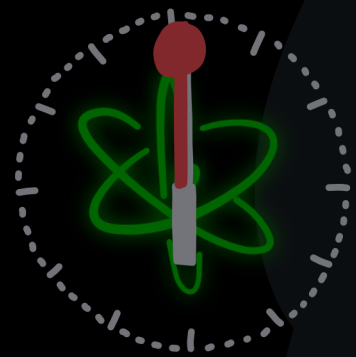


new
parameter η

generated by T

$$\partial_{\eta}\psi = i[T, \psi]$$

$|\psi(0)\rangle$



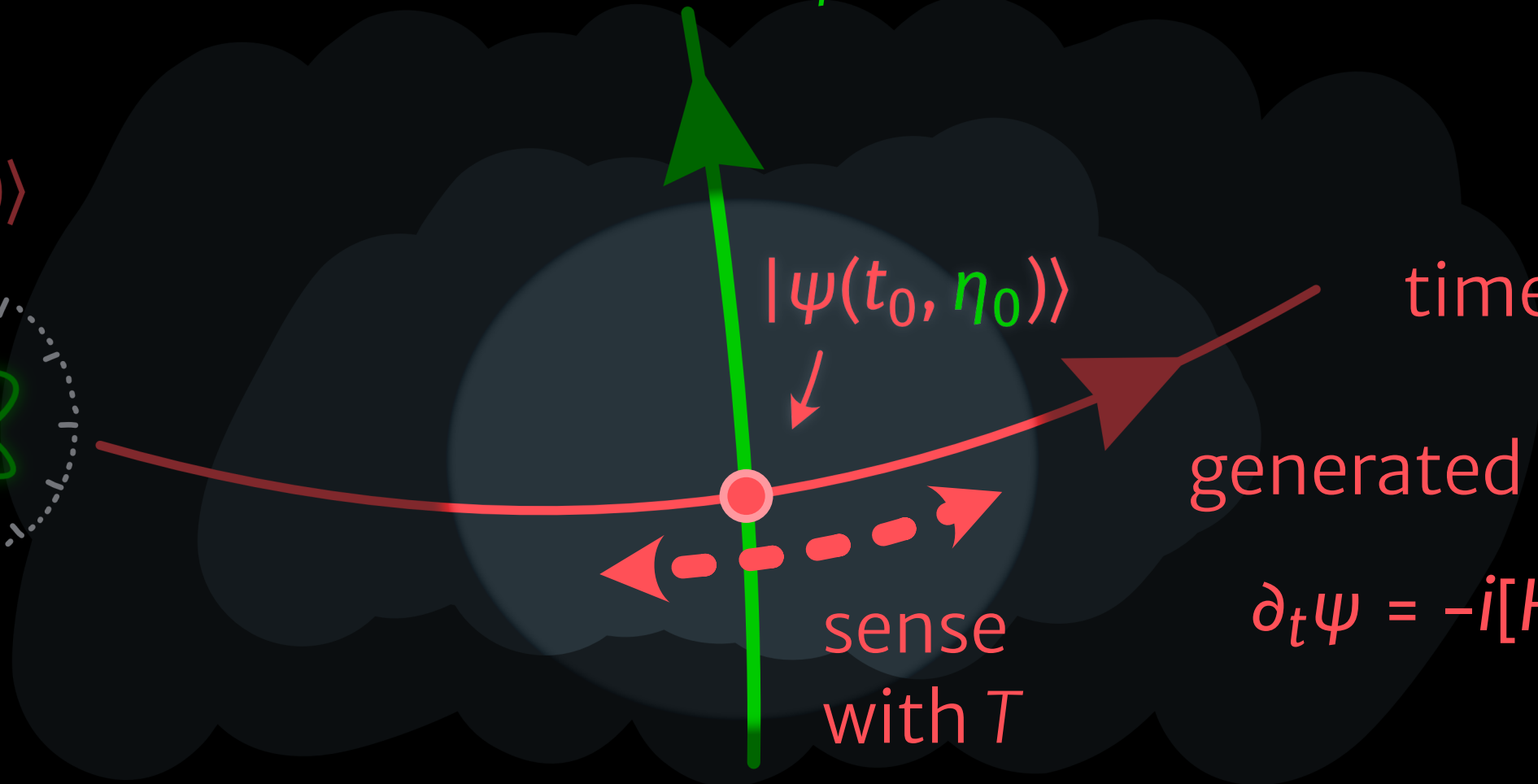
$|\psi(t_0, \eta_0)\rangle$

time t

generated by H

$$\partial_t\psi = -i[H, \psi]$$

sense
with T

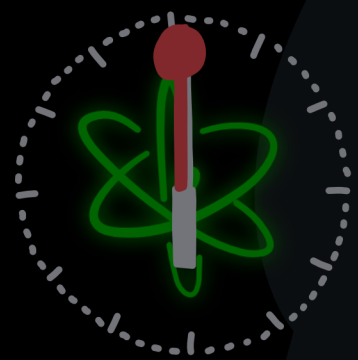


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sense
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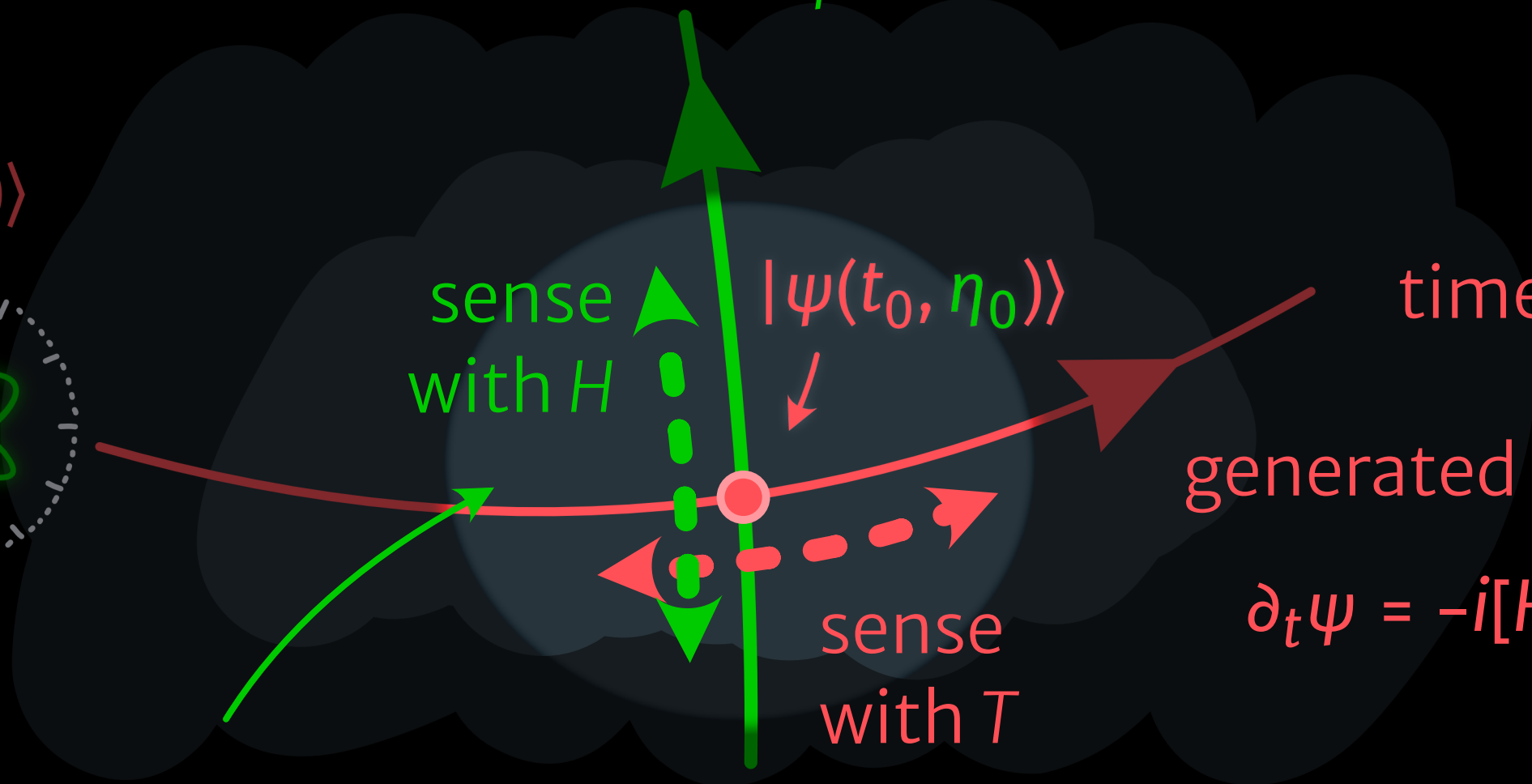
time t

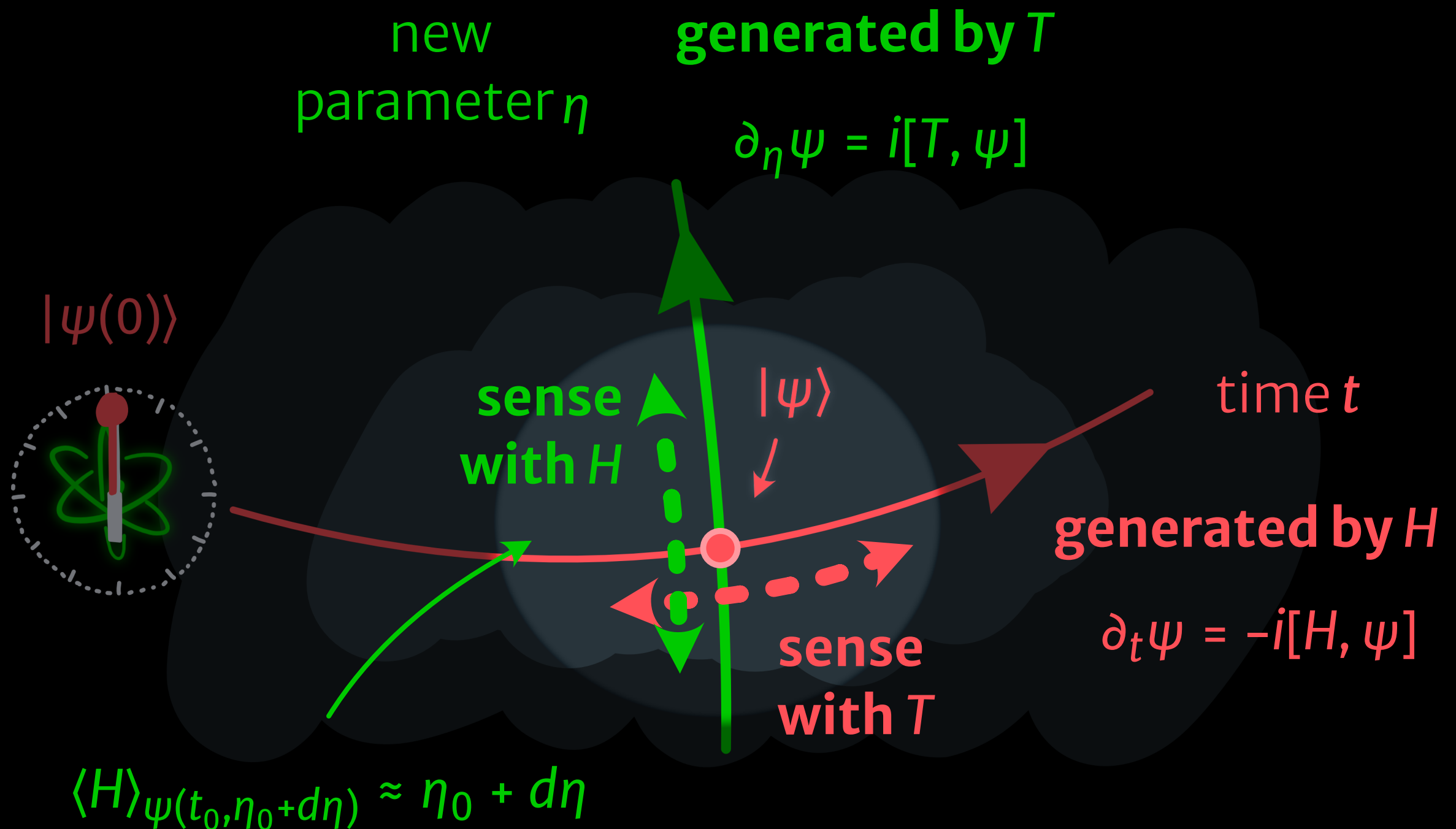
generated by H

$$\partial_t\psi = -i[H, \psi]$$

sense
with T

$$\langle H \rangle_{\psi(t_0, \eta_0 + d\eta)} \approx \eta_0 + d\eta$$





The η parameter represents energy, and is complementary to time t locally at $|\psi\rangle$

Alice



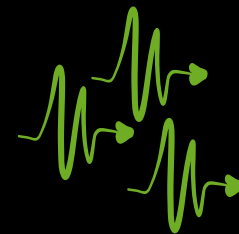
Bob



$$F_{\text{Bob},t} = F(\mathcal{N}(\psi); \mathcal{N}(\partial_t \psi))$$



*complementary
channel*



Eve

$$F_{\text{Eve},\eta} = F(\mathcal{N}(\psi); \mathcal{N}(\partial_\eta \psi))$$

Alice



Bob



*complementary
channel*

Eve

$$F_{\text{Bob},t} = F(\mathcal{N}(\psi); \mathcal{N}(\partial_t \psi))$$

$$F_{\text{Eve},\eta} = F(\mathcal{N}(\psi); \mathcal{N}(\partial_\eta \psi))$$

Main
Result

$$\frac{F_{\text{Bob},t}}{F_{\text{Alice},t}} + \frac{F_{\text{Eve},\eta}}{F_{\text{Alice},\eta}} = 1$$

*Fisher
information
tradeoff*

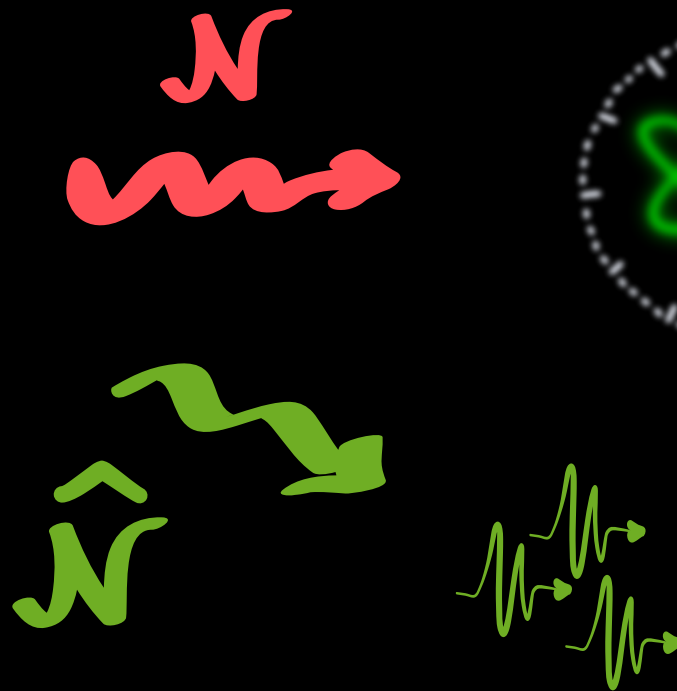
Alice



Bob



$$F_{\text{Bob},t} = F(\mathcal{N}(\psi); \mathcal{N}(\partial_t \psi))$$



$$F_{\text{Eve},\eta} = F(\mathcal{N}(\psi); \mathcal{N}(\partial_\eta \psi))$$

Eve

Bob's sensitivity to time

Eve's sensitivity to energy

Main
Result

$$\frac{F_{\text{Bob},t}}{F_{\text{Alice},t}} + \frac{F_{\text{Eve},\eta}}{F_{\text{Alice},\eta}} = 1$$

*Fisher
information
tradeoff*

make units consistent

Main
Result

$$\frac{F_{\text{Bob},t}}{F_{\text{Alice},t}} + \frac{F_{\text{Eve},\eta}}{F_{\text{Alice},\eta}} = 1$$

$$F_{\text{Alice},t} = 4\sigma_H^2 \quad F_{\text{Alice},\eta} = \sigma_H^{-2}$$



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$$F_{\text{Bob},t} = F_{\text{Alice},t} - \frac{F_{\text{Alice},t}}{F_{\text{Alice},\eta}} F_{\text{Eve},\eta}$$

noiseless
sensitivity
 $= 4\sigma_H^2$

$=: G$
sensitivity
loss

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$$G = 4\sigma_H^4 F_{\text{Eve},\eta} = F(\hat{\mathcal{N}}(\psi); \hat{\mathcal{N}}(\{\bar{H}, \psi\}))$$

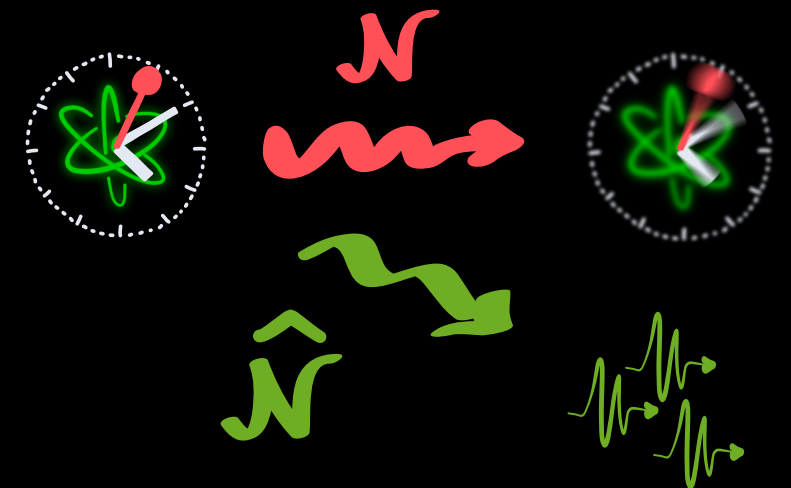
$$\partial_\eta \psi = \frac{\{\bar{H}, \psi\}}{2\sigma_H^2}$$

➤ Decrease in Fisher information can be computed from Eve's system

Main Result

$$\frac{F_{\text{Bob},t}}{F_{\text{Alice},t}} + \frac{F_{\text{Eve},\eta}}{F_{\text{Alice},\eta}} = 1$$

$$F_{\text{Alice},t} = 4\sigma_H^2 \quad F_{\text{Alice},\eta} = \sigma_H^{-2}$$



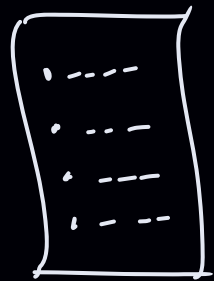
$$F_{\text{Bob},t} = \underbrace{F_{\text{Alice},t}}_{\text{noiseless sensitivity} = 4\sigma_H^2} - \underbrace{\frac{F_{\text{Alice},t}}{F_{\text{Alice},\eta}} F_{\text{Eve},\eta}}_{=: G \text{ sensitivity loss}}$$

$$\partial_\eta \psi = \frac{\{\bar{H}, \psi\}}{2\sigma_H^2}$$

$$G = 4\sigma_H^4 F_{\text{Eve},\eta} = F(\hat{\mathcal{N}}(\psi); \hat{\mathcal{N}}(\{\bar{H}, \psi\}))$$

➤ Decrease in Fisher information can be computed from Eve's system

➤ e.g. interesting for local, weak noise on a many-body system



Main proof ingredients

Variational characterization of the Fisher information

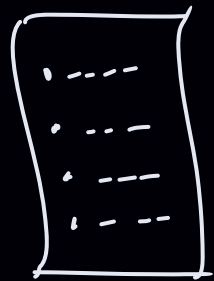
$$\begin{aligned}\frac{1}{4}F(\rho; D) &= \max_{S=S^\dagger} [\text{tr}(DS) - \text{tr}(\rho S^2)] \\ &= \min \{ \text{tr}(LL^\dagger) : \rho^{1/2}L + L^\dagger\rho^{1/2} = D \}\end{aligned}$$

Macieszczak

1312.1356;

Holevo 2011;

...



Main proof ingredients

Variational characterization of the Fisher information

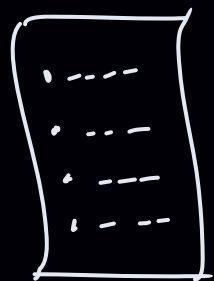
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Connection to Fidelity / Bures metric

$$F(\rho(t_0); \partial_t \rho(t_0)) = -8 \left. \frac{d^2}{dt^2} F(\rho(t_0), \rho(t)) \right|_{t_0}$$

Fidelity of quantum states



Main proof ingredients

Variational characterization of the Fisher information

$$\begin{aligned}\frac{1}{4}F(\rho; D) &= \max_{S=S^\dagger} [\text{tr}(DS) - \text{tr}(\rho S^2)] \\ &= \min \{ \text{tr}(LL^\dagger) : \rho^{1/2}L + L^\dagger\rho^{1/2} = D \}\end{aligned}$$

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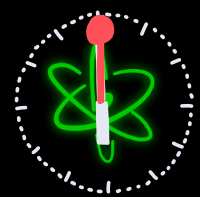
Fidelity of quantum states

Uhlmann:

$$F(\mathcal{N}(\psi), \mathcal{N}(\psi')) = \max_{W_E} |\langle \psi | V^\dagger (\mathbb{1} \otimes W_E) V | \psi' \rangle|$$

unitary on environment $\nearrow$ *dilation of $\mathcal{N}$* $\nearrow$

optim. over W_E
 $\leftrightarrow$ *optim. over S*



Example: 1 qubit

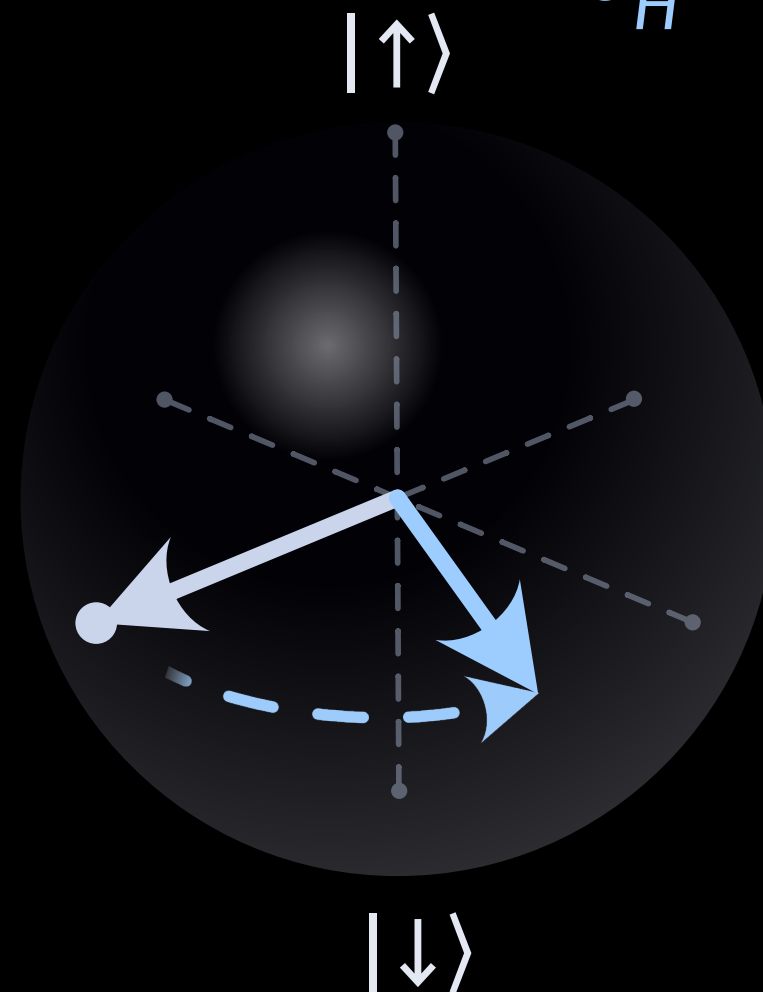
$$H = \frac{\omega}{2} \sigma_Z \quad |\psi\rangle = \frac{1}{\sqrt{2}} [|\uparrow\rangle + |\downarrow\rangle]$$

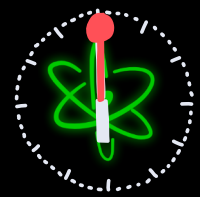
$$4\sigma_H^2 = \omega^2$$



Evolve for t_0 :

$$\psi_t = \frac{1}{2} \begin{bmatrix} 1 & e^{-i\omega t} \\ e^{i\omega t} & 1 \end{bmatrix}$$





Example: 1 qubit

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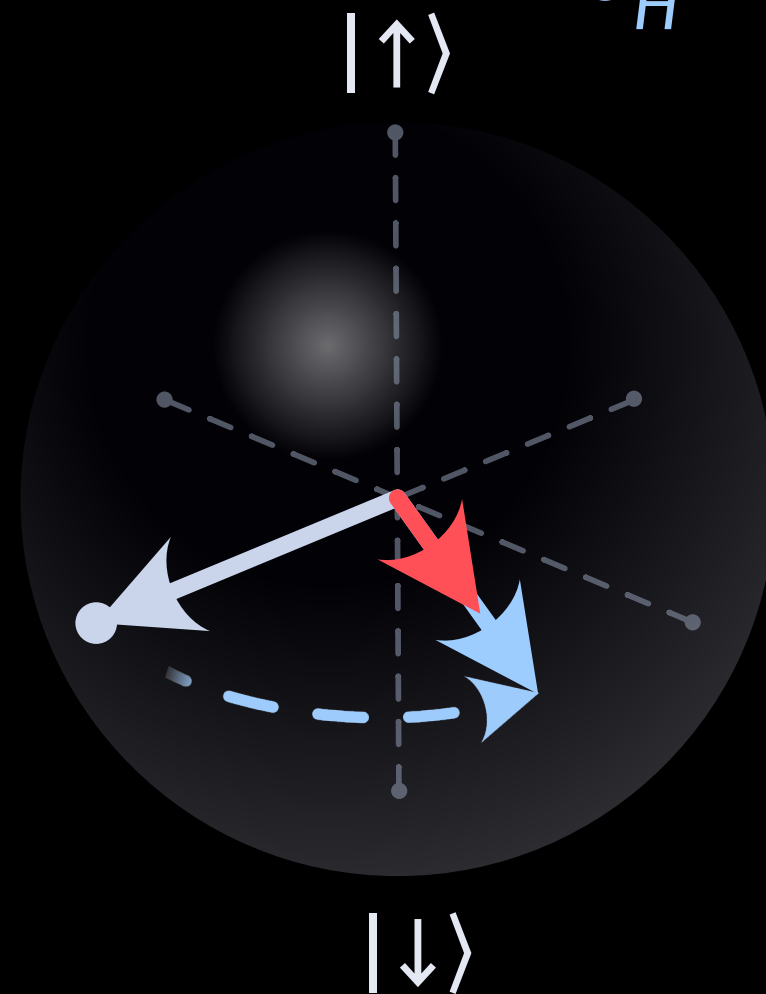
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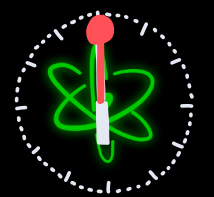
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Apply partial dephasing

$$\mathcal{D}_p[\rho] = \begin{bmatrix} \rho_{00} & (1-p)\rho_{01} \\ (1-p)\rho_{10} & \rho_{11} \end{bmatrix}$$





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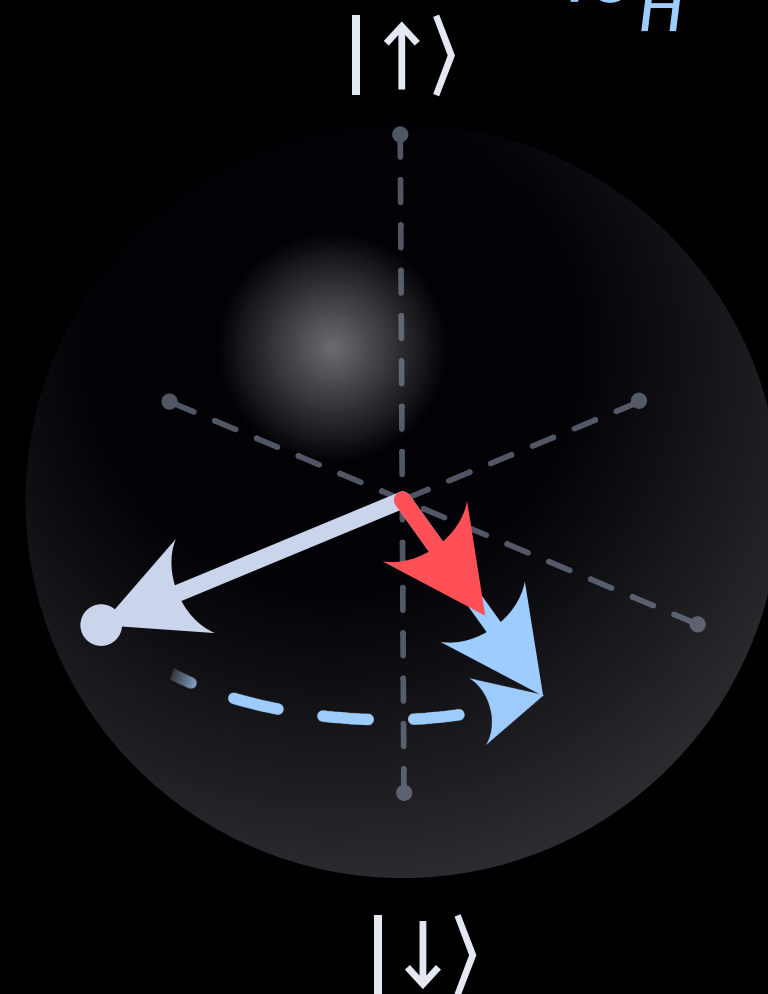


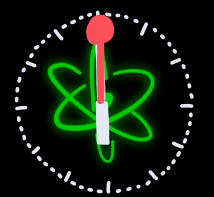
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Eve:

$$\hat{\mathcal{D}}_p[\rho] = \begin{bmatrix} (1 - \frac{p}{2}) \text{tr}(\rho) & \sqrt{\frac{p}{2}(1 - \frac{p}{2})} \text{tr}(\sigma_Z \rho) \\ \sqrt{\frac{p}{2}(1 - \frac{p}{2})} \text{tr}(\sigma_Z \rho) & \frac{p}{2} \text{tr}(\rho) \end{bmatrix}$$





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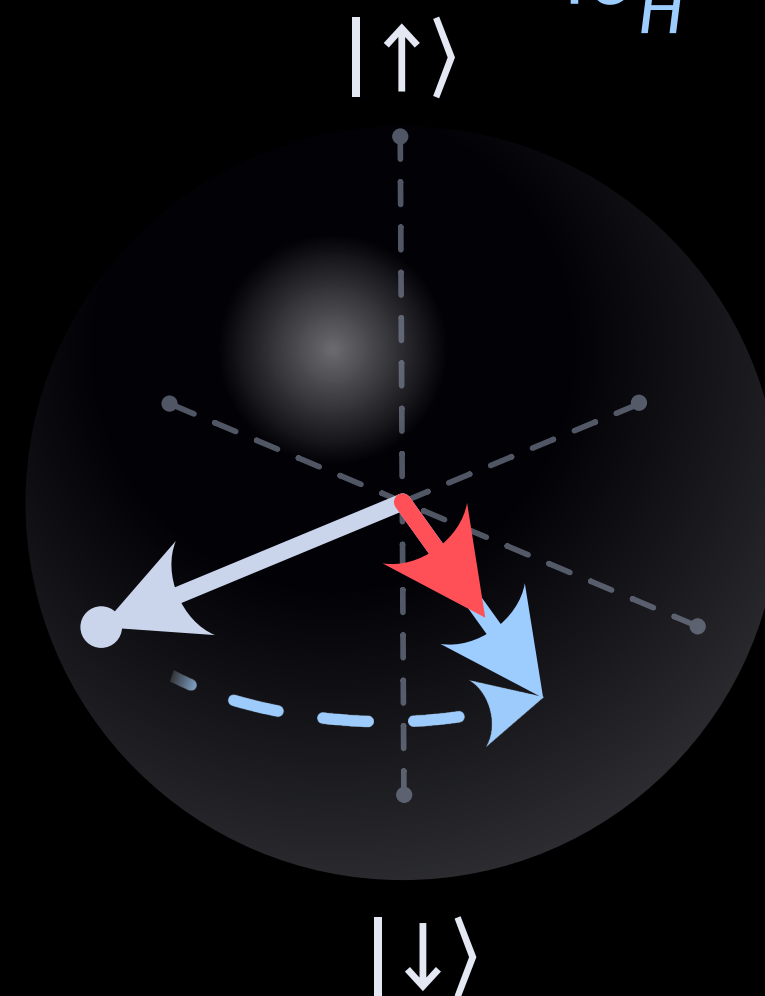
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sensitivity
loss:

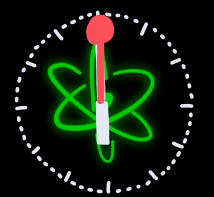
$$G = F(\hat{\mathcal{N}}(\psi); \hat{\mathcal{N}}(\{\bar{H}, \psi\})) = \omega^2 [1 - (1-p)^2]$$

$$\begin{pmatrix} 1 - \frac{p}{2} & 0 \\ 0 & \frac{p}{2} \end{pmatrix} \uparrow$$

$$\uparrow \omega \sqrt{\frac{p}{2}(1 - \frac{p}{2})} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$



$$\{\bar{H}, \psi\} = \frac{\omega}{2} \sigma_Z$$



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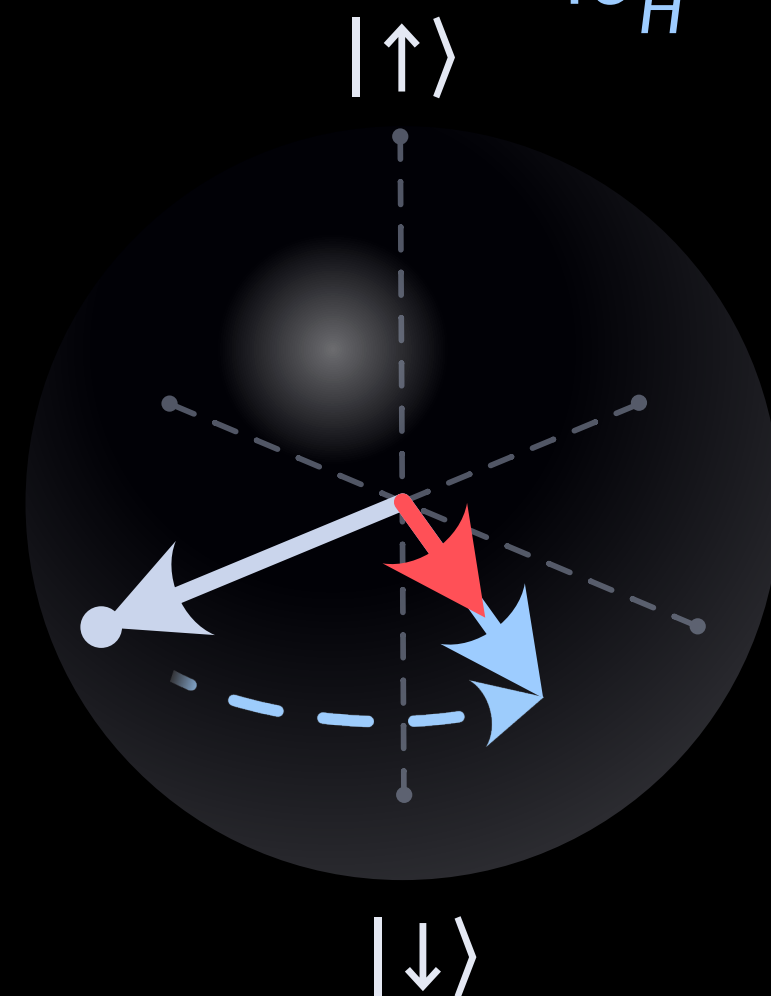
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loss:

$$G = F(\hat{\mathcal{N}}(\psi); \hat{\mathcal{N}}(\{\bar{H}, \psi\})) = \omega^2 [1 - (1-p)^2]$$

Direct calculation:

$$F_{\text{Bob},t} = \omega^2 (1-p)^2$$

$$F_{\text{Alice},t} = \omega^2$$





Uncertainty
relation for
sensitivity:

noisy clock
w.r.t. time

$\langle \rangle$

environment
w.r.t. energy



Expression for sensitivity loss

*(methods from
semidefinite
programming)*

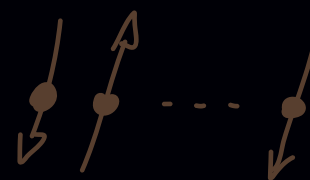
› alternative
sensitivity
bounds

› uncertainty
relation for any
two parameters

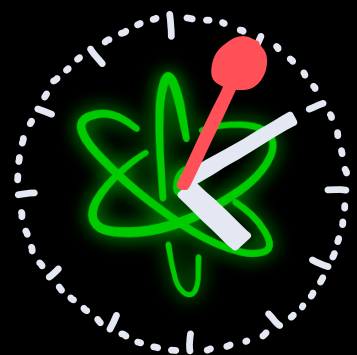
Ø1

Necessary and sufficient
conditions for zero
sensitivity loss

› “metrological codes”



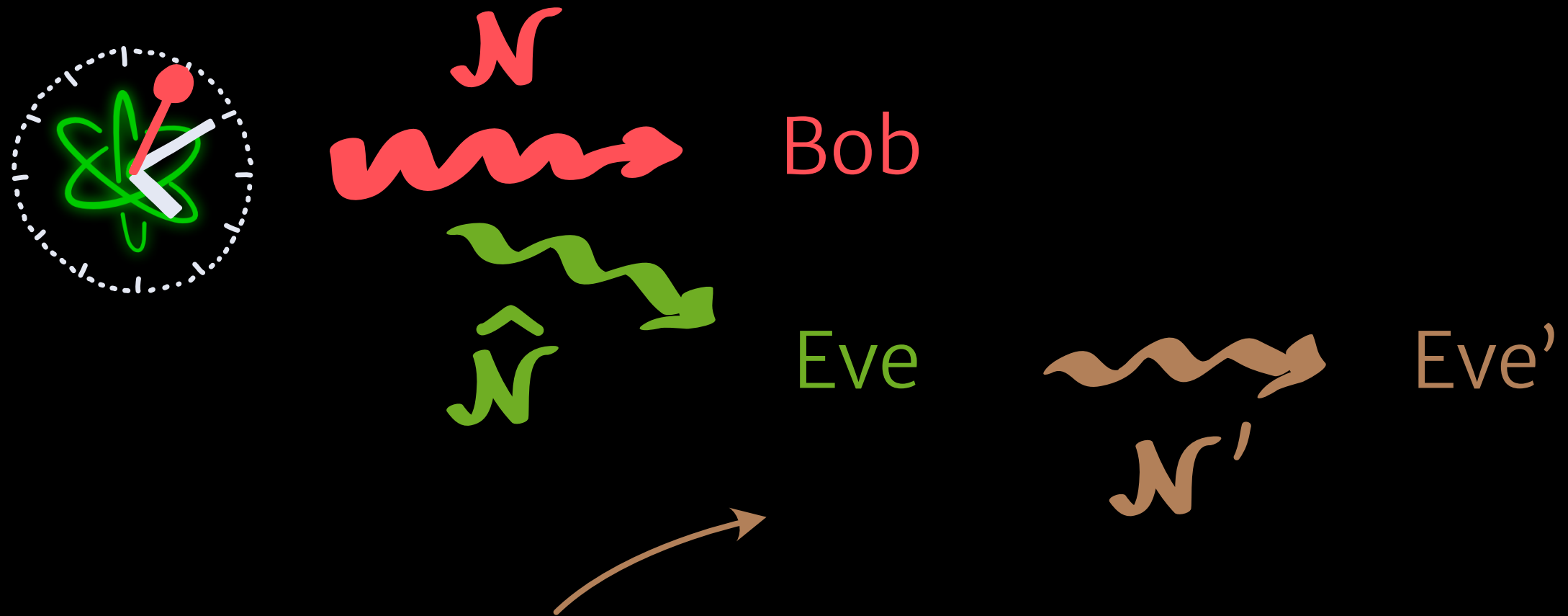
Example: Ising
Hamiltonian &
amplitude
damping noise



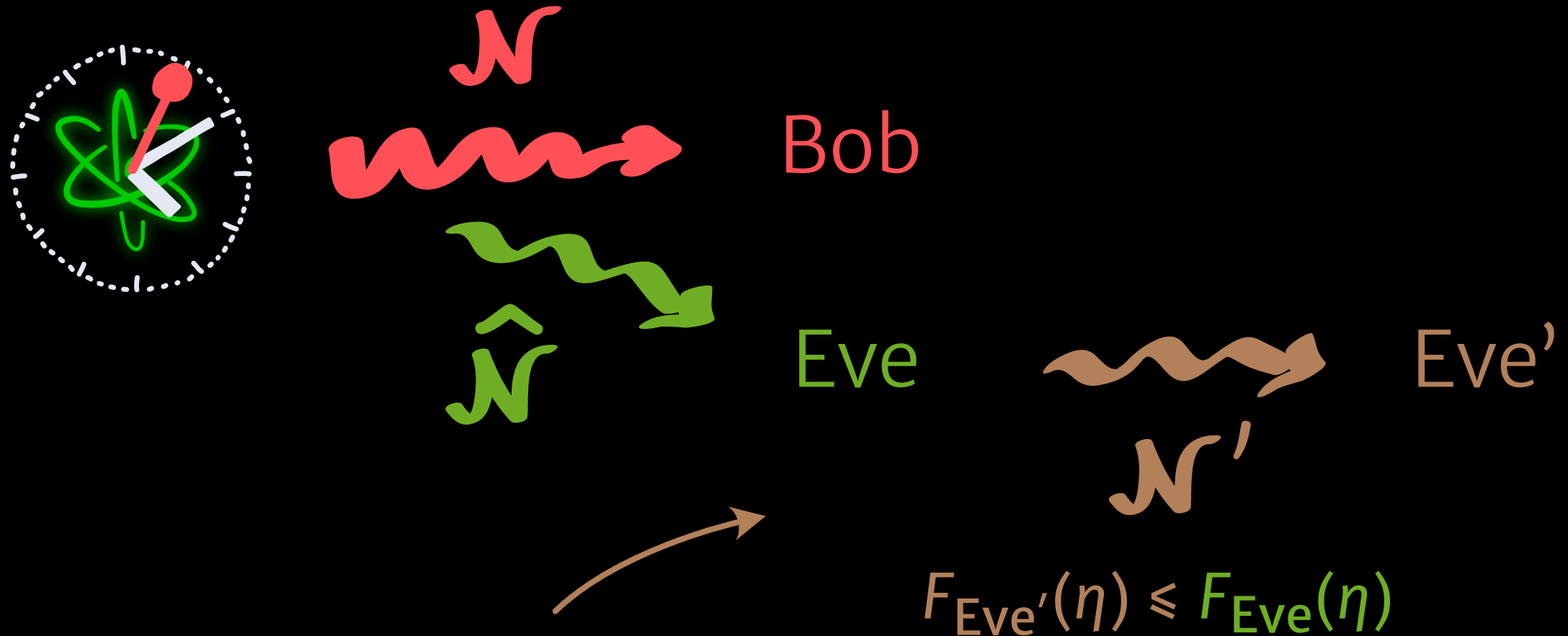
Bob



Eve



e.g., decohere in fixed basis
→ simpler bound for
amplitude damping noise



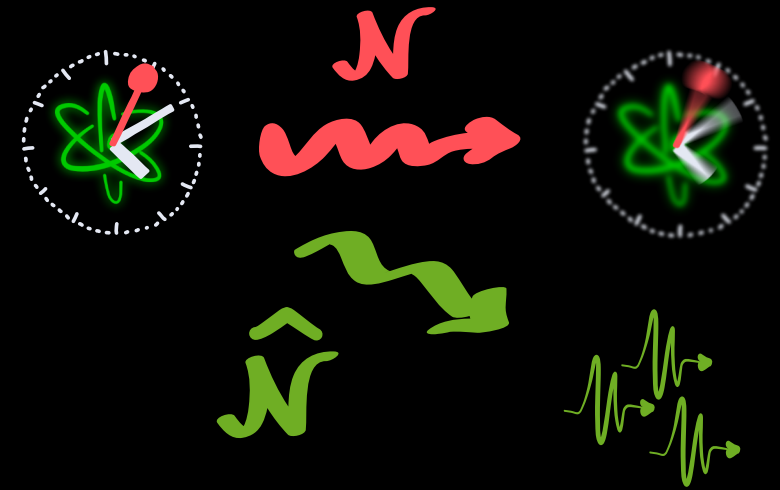
e.g., decohere in fixed basis
 → simpler bound for
 amplitude damping noise

$$\rightarrow \frac{F_{\text{Bob}}(t)}{F_{\text{Alice}}(t)} \leq 1 - \frac{F_{\text{Eve}'(\eta)}}{F_{\text{Alice}}(t)}$$

any two generators H, Z :

$$\partial_t \psi = -i[H, \psi]$$

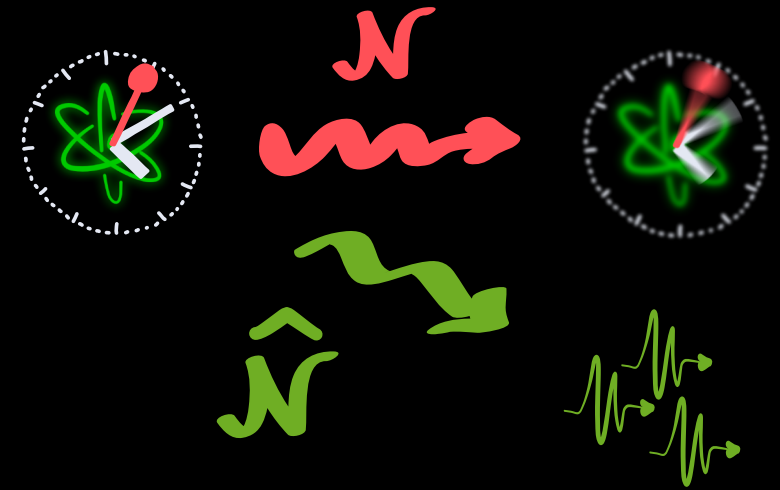
$$\partial_Z \psi = -i[Z, \psi]$$



any two generators H, Z :

$$\partial_t \psi = -i[H, \psi]$$

$$\partial_Z \psi = -i[Z, \psi]$$



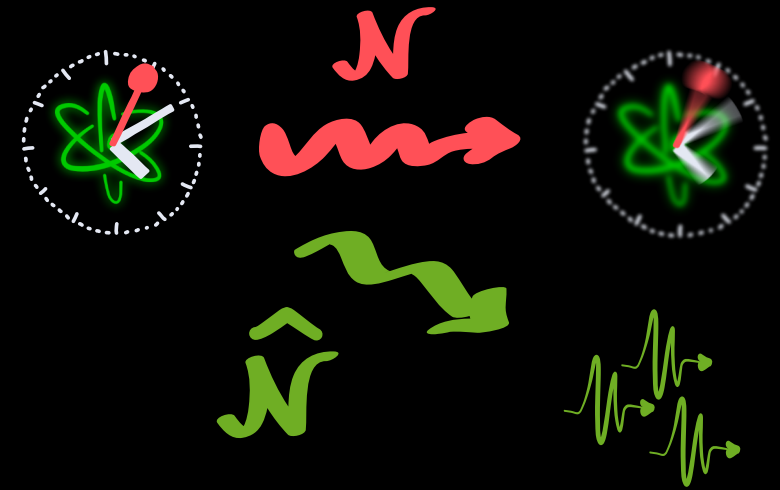
$$\frac{F_{\text{Bob}}(t)}{F_{\text{Alice}}(t)} + \frac{F_{\text{Eve}}(Z)}{F_{\text{Alice}}(Z)} \leq 1 + 2 \sqrt{1 - \frac{\langle i[H, Z] \rangle^2}{4 \sigma_H^2 \sigma_Z^2}}$$

Fisher information
tradeoff for any
two parameters

any two generators H, Z :

$$\partial_t \psi = -i[H, \psi]$$

$$\partial_Z \psi = -i[Z, \psi]$$



$$\frac{F_{\text{Bob}}(t)}{F_{\text{Alice}}(t)} + \frac{F_{\text{Eve}}(Z)}{F_{\text{Alice}}(Z)} \leq 1 + 2 \underbrace{\sqrt{1 - \frac{\langle i[H, Z] \rangle^2}{4 \sigma_H^2 \sigma_Z^2}}}$$

Fisher information
tradeoff for any
two parameters

= 0 if H, Z saturate the
Robertson uncertainty relation

$$\sigma_H \sigma_Z \geq \frac{1}{2} |\langle i[H, Z] \rangle|$$

(e.g., energy & time)



Uncertainty
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sensitivity:

noisy clock
w.r.t. time

$\langle \rangle$

environment
w.r.t. energy



Expression for sensitivity loss

*(methods from
semidefinite
programming)*

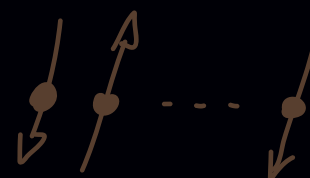
➤ alternative
sensitivity
bounds

➤ uncertainty
relation for any
two parameters

Ø1

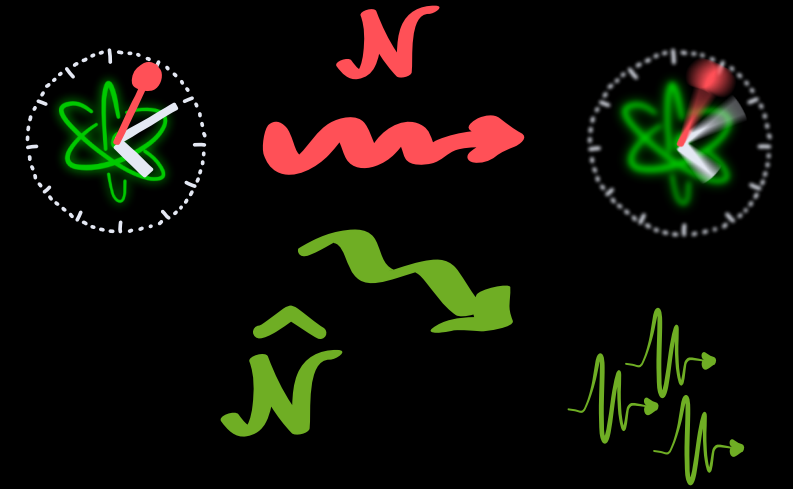
Necessary and sufficient
conditions for zero
sensitivity loss

➤ “metrological codes”



Example: Ising
Hamiltonian &
amplitude
damping noise

when is no sensitivity lost?



$$F_{\text{Eve},\eta} = 0 \quad ?$$

when is no sensitivity lost?



$$F_{\text{Eve},\eta} = 0$$



$$\text{tr}[\mathbf{Z} \Pi E_{k'}^\dagger E_k \Pi] = 0$$

like
Knill–Laflamme,
but weaker

“code qubit”
spanned by
 $|\psi\rangle =: |+\rangle$ and $\bar{H}|\psi\rangle$

when is no sensitivity lost?



$$F_{\text{Eve},\eta} = 0$$



$$\text{tr}\left[Z \Pi E_{k'}^\dagger E_k \Pi\right] = 0$$

“code qubit”
spanned by

$$|\psi\rangle =: |+\rangle \text{ and } \bar{H}|\psi\rangle$$

like
Knill–Laflamme,
but weaker

closely related to:

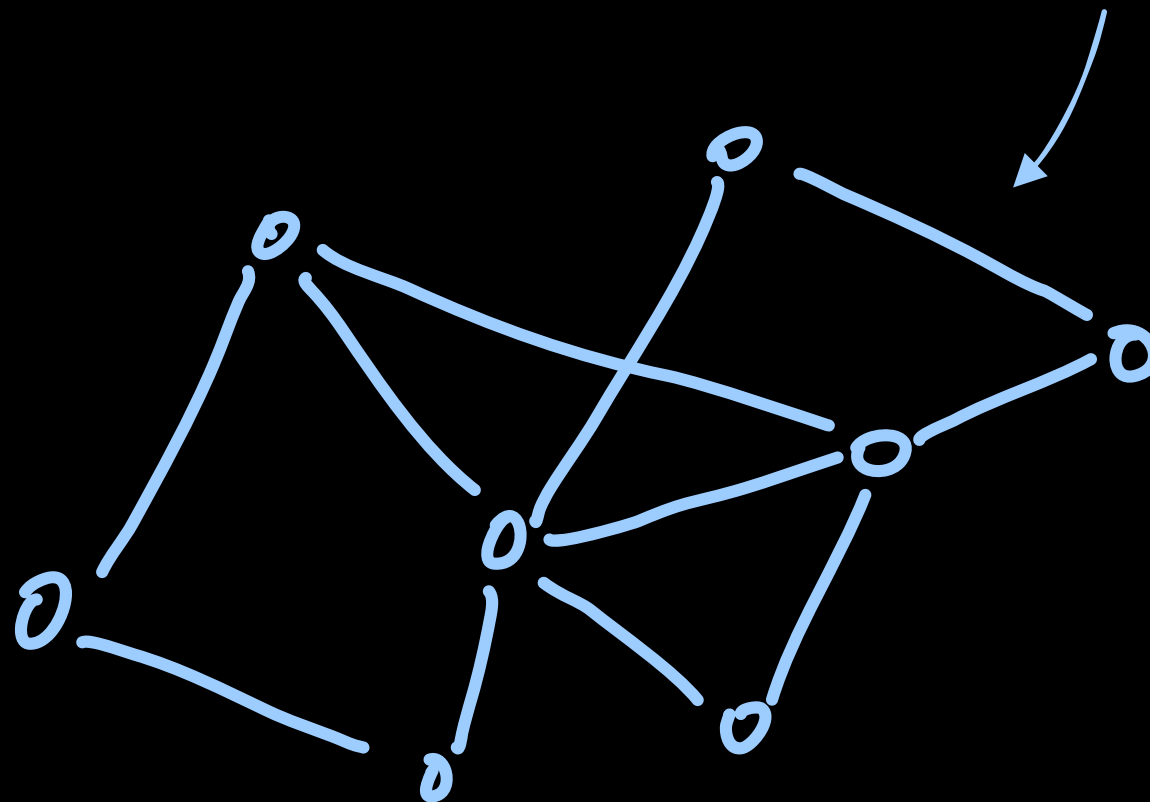
Hamiltonian not in
Lindblad span
quantum error
correction for algebras

Demkowicz–Dobrzański+ PRX 2017;
Zhou+ N. Comm. 2018; Layden+ PRL 2019;

...

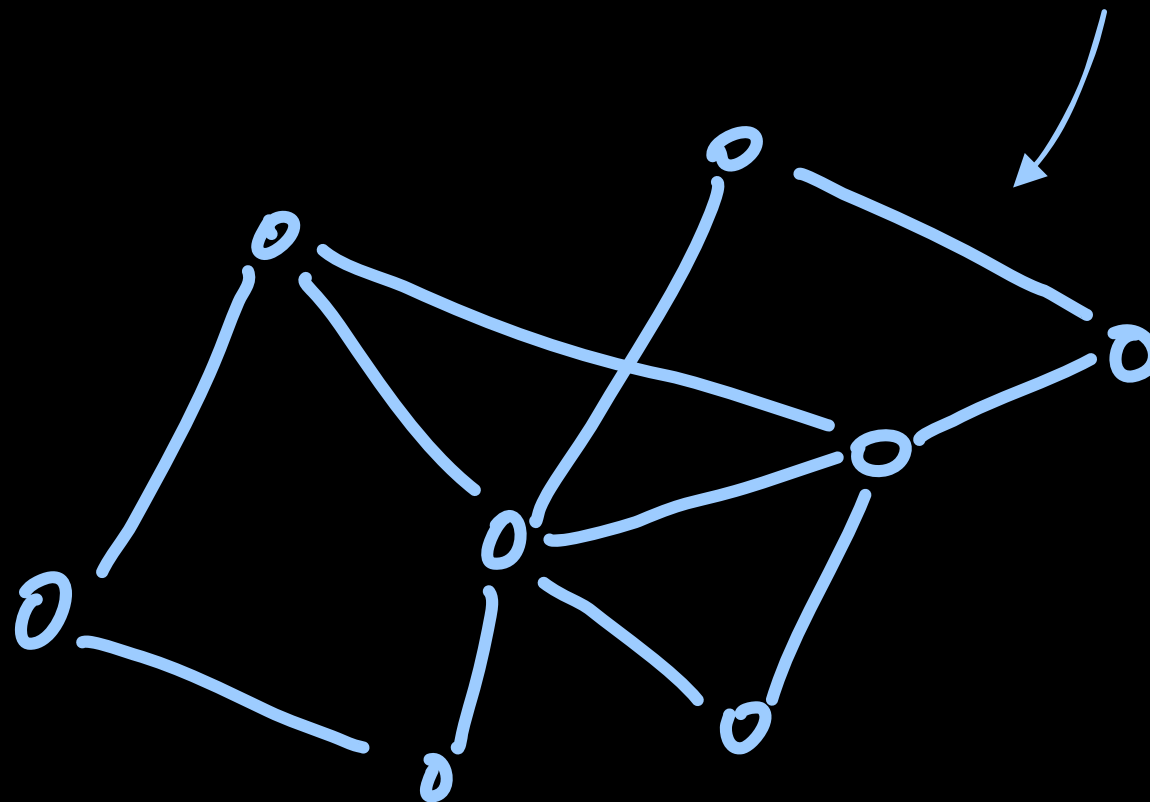
Bény+ PRL 2007

ZZ interactions
(can also include XX & YY)



cf. e.g. Ouyang
1908.02378; ...

ZZ interactions
(can also include XX & YY)



cf. e.g. Ouyang
1908.02378; ...

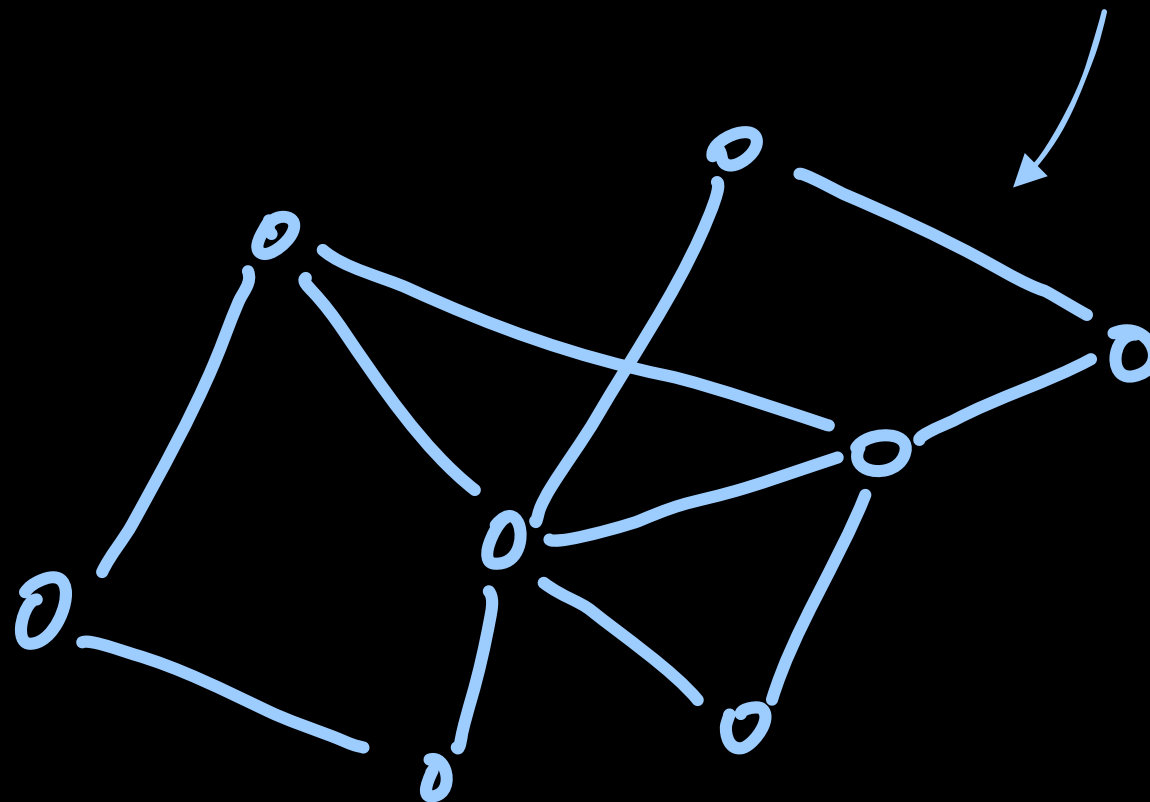
$$|\psi\rangle = \frac{1}{\sqrt{2}} [|0 \dots 0\rangle + |c^n\rangle]$$

c^n = configuration that violates
many interaction terms

$$\text{tr}[Z \Pi E_{k'}^\dagger E_k \Pi] \neq 0 \quad \times$$

prone to sensitivity loss

ZZ interactions
(can also include XX & YY)



cf. e.g. Ouyang
1908.02378; ...

$$|\psi\rangle = \frac{1}{2} \left[|0 \dots 0\rangle + |1 \dots 1\rangle + |c^n\rangle + |c^{\bar{n}}\rangle \right]$$

c^n = configuration that violates many interaction terms

$$\text{tr}[Z \Pi E_{k'}^\dagger E_k \Pi] = 0 \quad \checkmark$$

no sensitivity loss in case of a single localized error



Uncertainty
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noisy clock
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Expression for sensitivity loss

*(methods from
semidefinite
programming)*

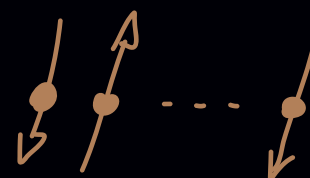
➤ alternative
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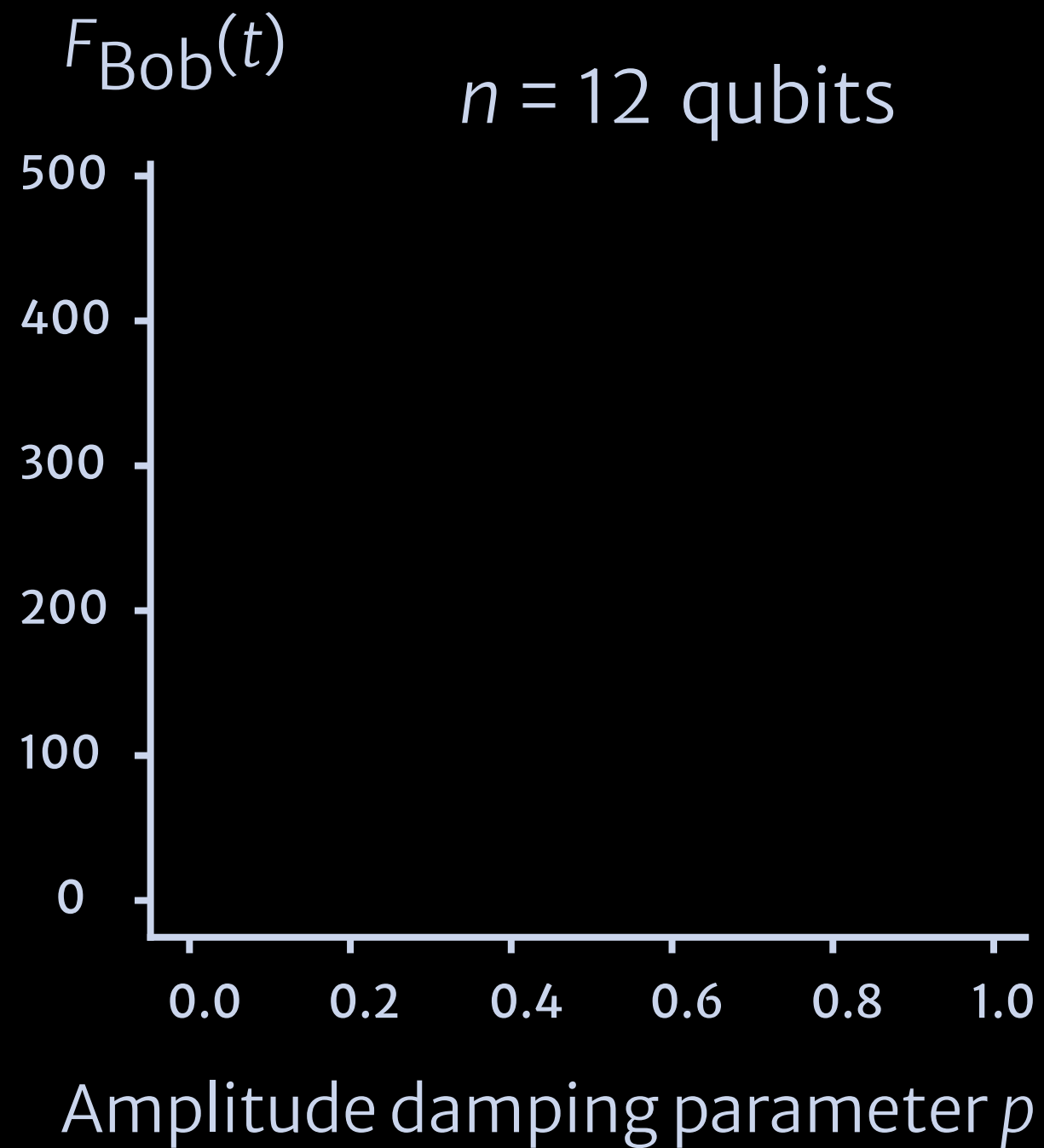
Necessary and sufficient
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➤ “metrological codes”

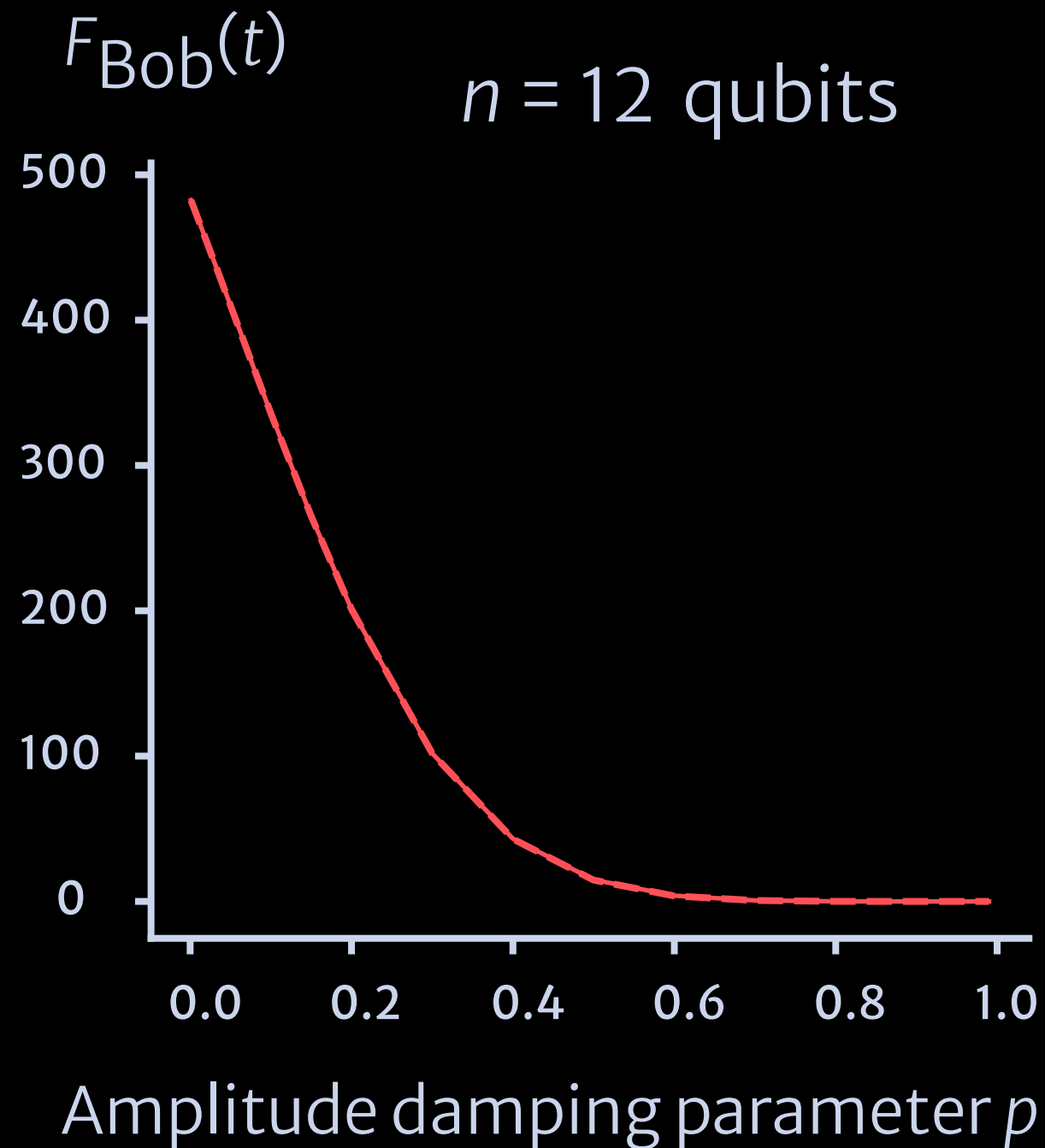


Example: Ising
Hamiltonian &
amplitude
damping noise

$$H = \sum \sigma_Z^{(j)} \sigma_Z^{(j+1)} \quad \text{1D spin chain}$$



$$H = \sum \sigma_Z^{(j)} \sigma_Z^{(j+1)} \quad \text{1D spin chain}$$



ferromagnet-
antiferromagnet state

$$|\psi\rangle = \frac{1}{\sqrt{2}}(|00 \dots 00\rangle + |01 \dots 01\rangle)$$

$$H = \sum \sigma_Z^{(j)} \sigma_Z^{(j+1)}$$

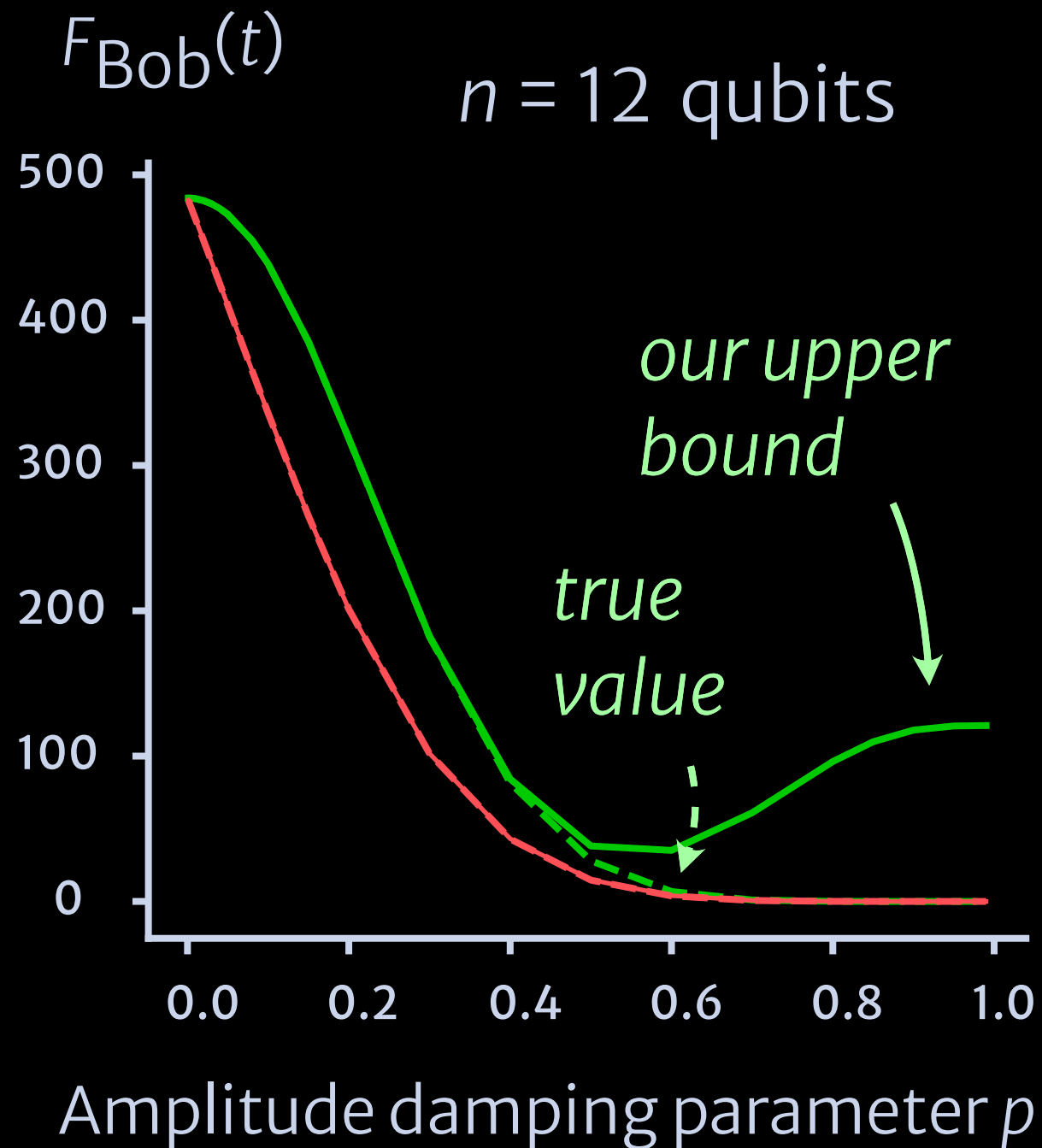
1D spin chain

ferromagnet-
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$$|\psi\rangle = \frac{1}{\sqrt{2}}(|00 \dots 00\rangle + |01 \dots 01\rangle)$$

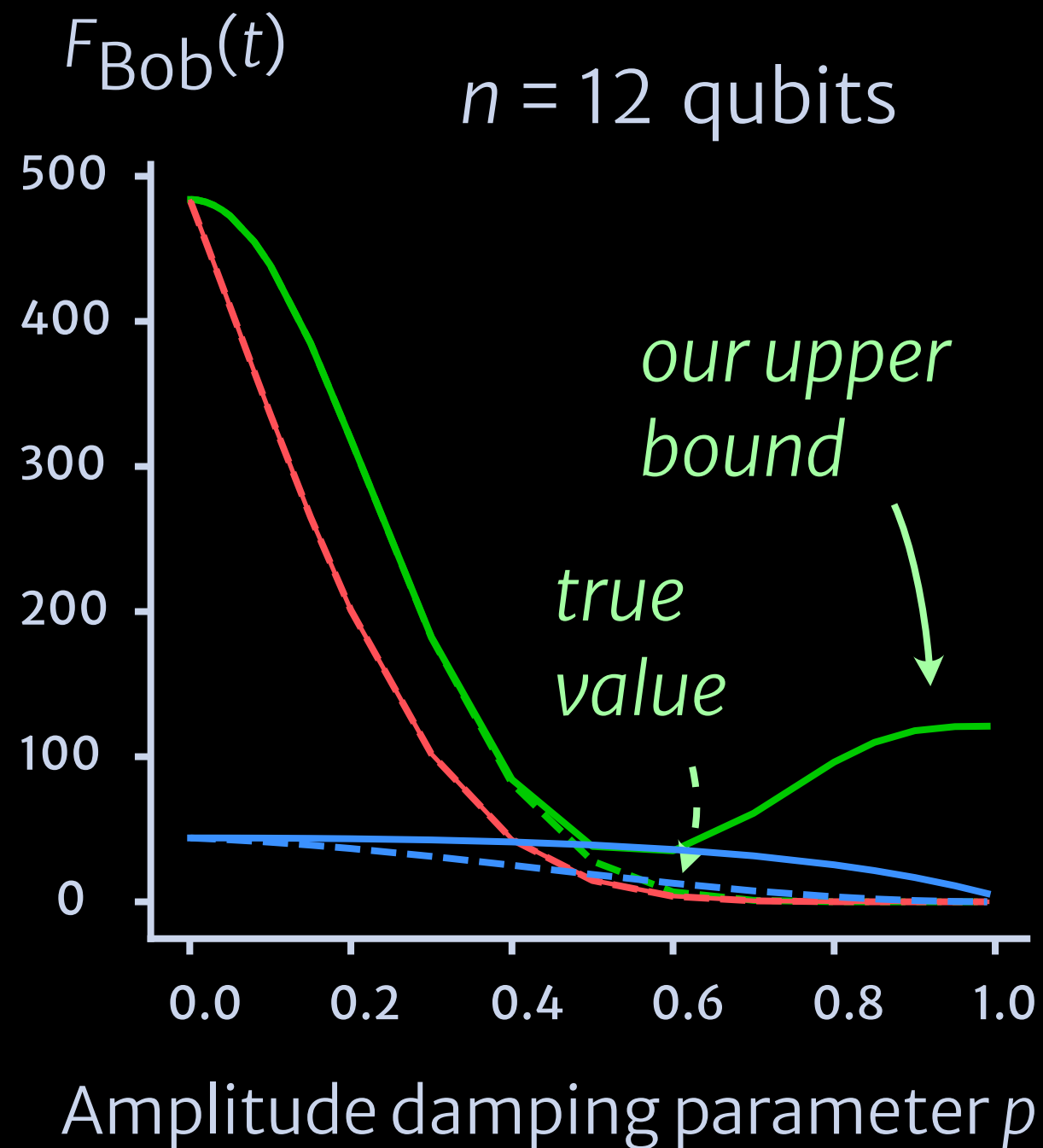
“metrological code state”

$$|\psi\rangle = \frac{1}{2}(|00 \dots 00\rangle + |11 \dots 11\rangle + |01 \dots 01\rangle + |10 \dots 10\rangle)$$



$$H = \sum \sigma_Z^{(j)} \sigma_Z^{(j+1)}$$

1D spin chain



ferromagnet-
antiferromagnet state

$$|\psi\rangle = \frac{1}{\sqrt{2}}(|00 \dots 00\rangle + |01 \dots 01\rangle)$$

“metrological code state”

$$|\psi\rangle = \frac{1}{2}(|00 \dots 00\rangle + |11 \dots 11\rangle + |01 \dots 01\rangle + |10 \dots 10\rangle)$$

spin-coherent (clock) state

$$|\psi\rangle = |+\rangle^{\otimes n}$$

$$H = \sum \sigma_Z^{(j)} \sigma_Z^{(j+1)}$$

1D spin chain

ferromagnet-
antiferromagnet state

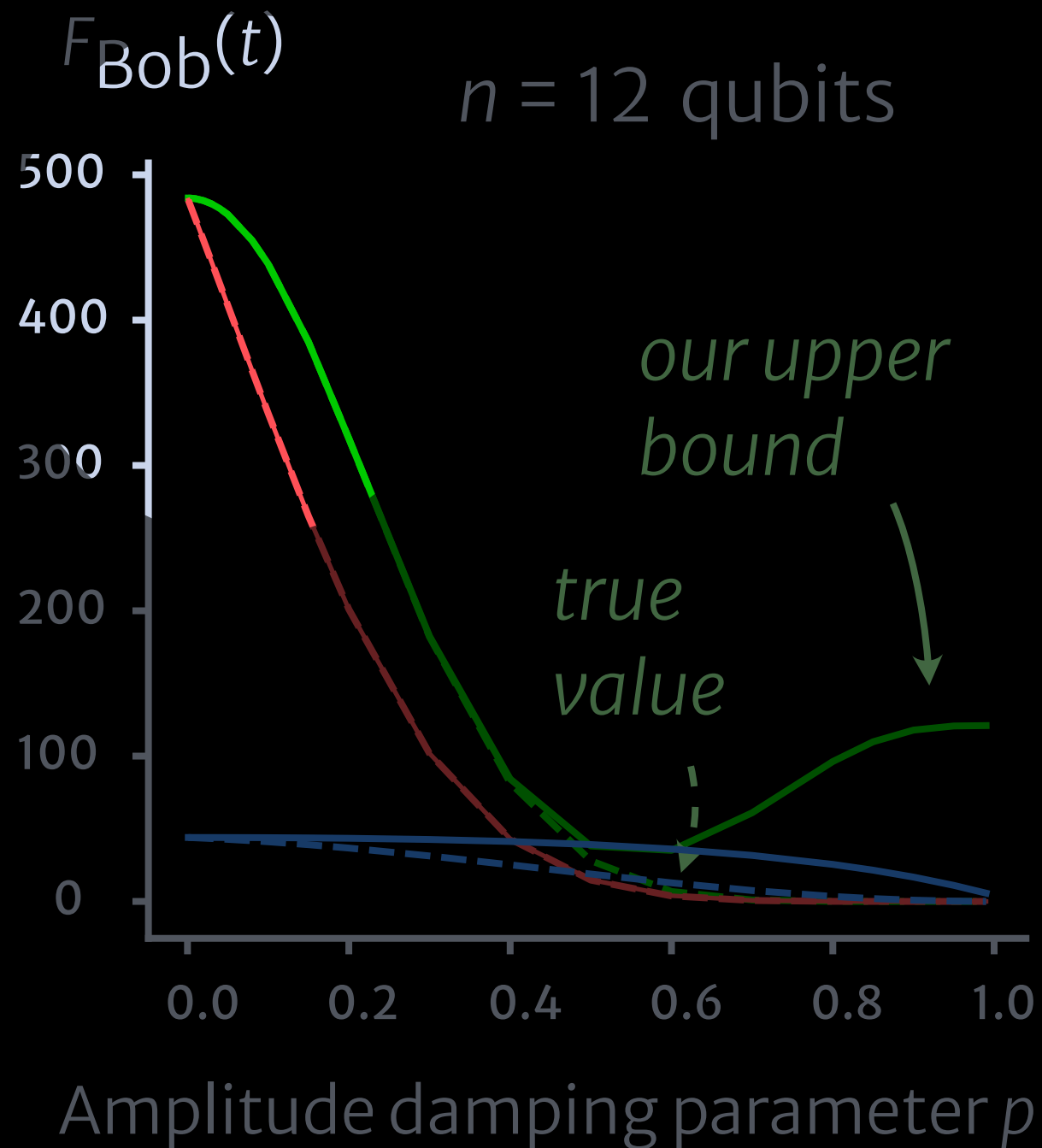
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$$|\psi\rangle = \frac{1}{2}(|00 \dots 00\rangle + |11 \dots 11\rangle + |01 \dots 01\rangle + |10 \dots 10\rangle)$$

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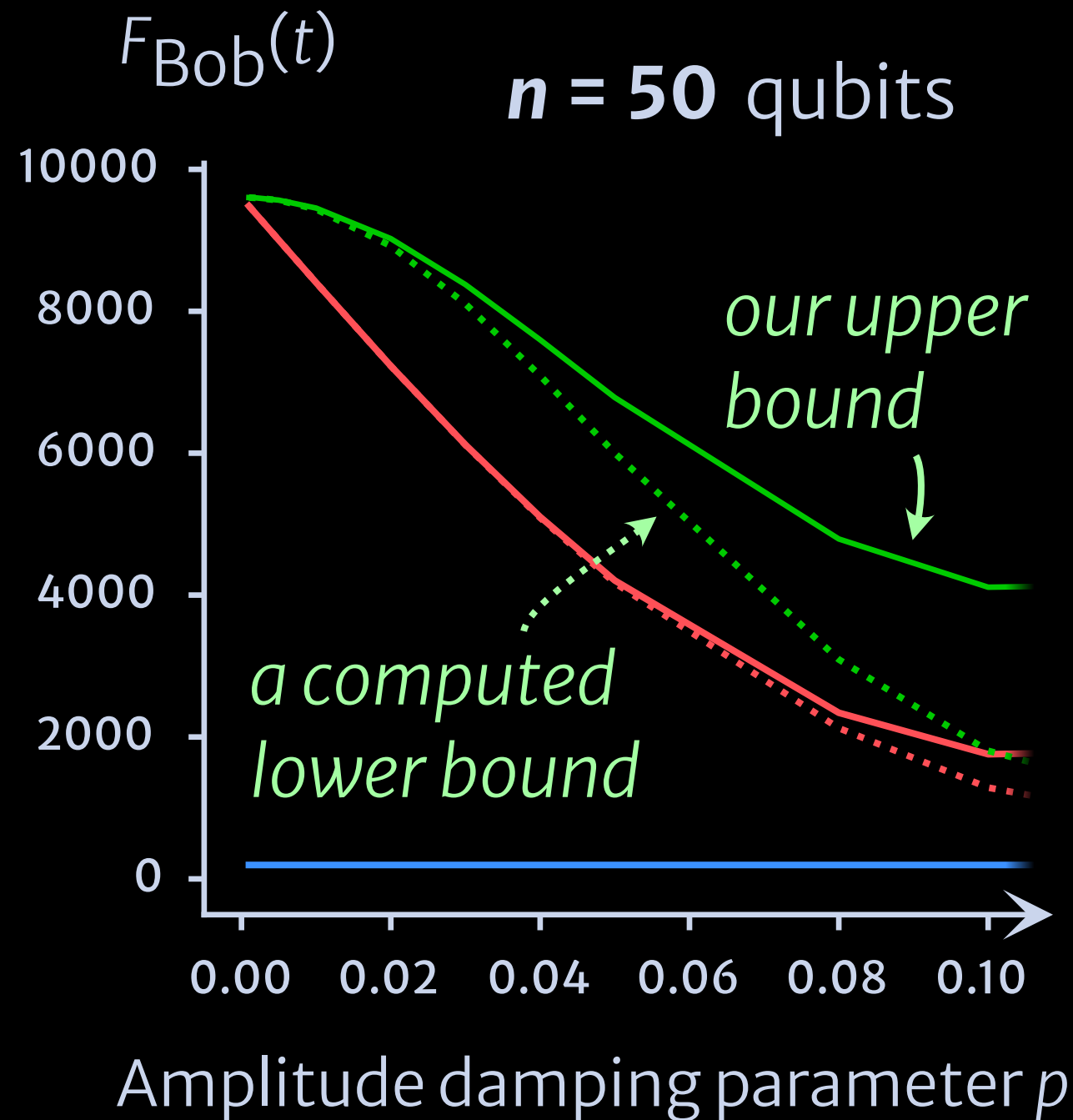
$$|\psi\rangle = |+\rangle^{\otimes n}$$



$$H = \sum \sigma_Z^{(j)} \sigma_Z^{(j+1)}$$

1D spin chain

$n = 50$ qubits



ferromagnet-
antiferromagnet state

$$|\psi\rangle = \frac{1}{\sqrt{2}}(|00 \dots 00\rangle + |01 \dots 01\rangle)$$

“metrological code state”

$$|\psi\rangle = \frac{1}{2}(|00 \dots 00\rangle + |11 \dots 11\rangle + |01 \dots 01\rangle + |10 \dots 10\rangle)$$

spin-coherent (clock) state

$$|\psi\rangle = |+\rangle^{\otimes n}$$



Uncertainty
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Expression for sensitivity loss

*(methods from
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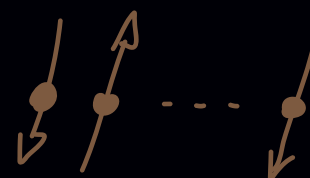
› alternative
sensitivity
bounds

› uncertainty
relation for any
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Ø1

Necessary and sufficient
conditions for zero
sensitivity loss

› “metrological codes”



Example: Ising
Hamiltonian &
amplitude
damping noise

- Better clock states = those that hide energy from Eve
- Our results hold for any fixed state $|\psi\rangle$
- Our uncertainty relations extend to infinite dimensions
- Also applicable for sensing an unknown parameter in the Hamiltonian
- Also applicable for continuous Markovian noise, under some additional assumptions

- Information tradeoffs / uncertainty relations give insight into the structure of quantum theory
- Fisher information counterpart to entropic uncertainty relations
Coles+ PRL 2019
- Characterization of the Fisher information in intermediate regimes of n (non-asymptotic)
- general Fisher information bounds can be hard to obtain
Fujiwara & Imai JPA 2008; Escher+ Nat Phys 2011; ...
- strongly interacting many-body probes might offer better sensitivity in quantum metrology
NV centers lattice atomic clocks
Zhou+ PRX 2020 Goban+ Nat. 2018

Applications to
cryptography?

Coles+ RMP 2017; ...

Multi-parameter
metrology?

Gorecki+ Quantum 2020; ...

sensitivity loss of
“metrological codes” for
weak i.i.d. noise?

Thank you for your attention!

$$\partial_t \rho = -\mathcal{L}(\rho) \quad \mathcal{L} = \mathcal{L}_0 + \mathcal{L}_1 \rightarrow \Sigma_t = e^{t\mathcal{L}} \text{ full evolution}$$

$\uparrow$ unitary $\mathcal{L}_0(\cdot) = -i[H, (\cdot)]$
 $\uparrow$ noise $\mathcal{L}_1(\rho) = \sum [L_j \rho L_j^\dagger - \frac{1}{2} \{L_j^\dagger L_j, \rho\}]$

Decompose Σ_t as unitary followed by

"effective noise channel" $\mathcal{N}_t$: $\Sigma_t = \mathcal{N}_t e^{t\mathcal{L}_0}$

$$|\psi_0\rangle \xrightarrow{e^{t\mathcal{L}}} \rho(t)$$

$$\hookrightarrow \mathcal{N}_t = \Sigma_t e^{-t\mathcal{L}_0}$$

$$|\psi_0\rangle \rightarrow \mathcal{U}_t |\psi_0\rangle \xrightarrow{\mathcal{N}_t} \rho(t)$$

Assume
 $\partial_t \mathcal{N}_t \ll \mathcal{N}_t(\partial_t \psi)$

$\rightarrow$ setting of our main result

$$F(\rho; \partial_t \rho) \approx 4\sigma_H^2 - F(\Sigma_t(\psi_0); \Sigma_t(\partial_t \psi_0))$$

