

# (Sub)Exponential advantage of adiabatic quantum computation with no sign problem

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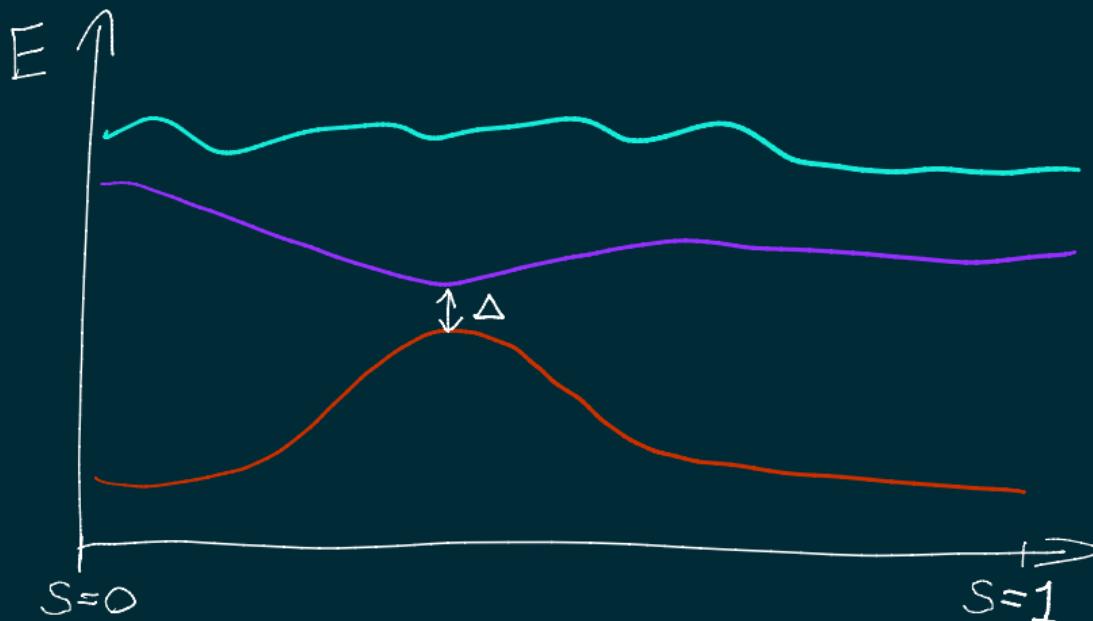
arXiv:2011.09495

## Adiabatic quantum computation – background

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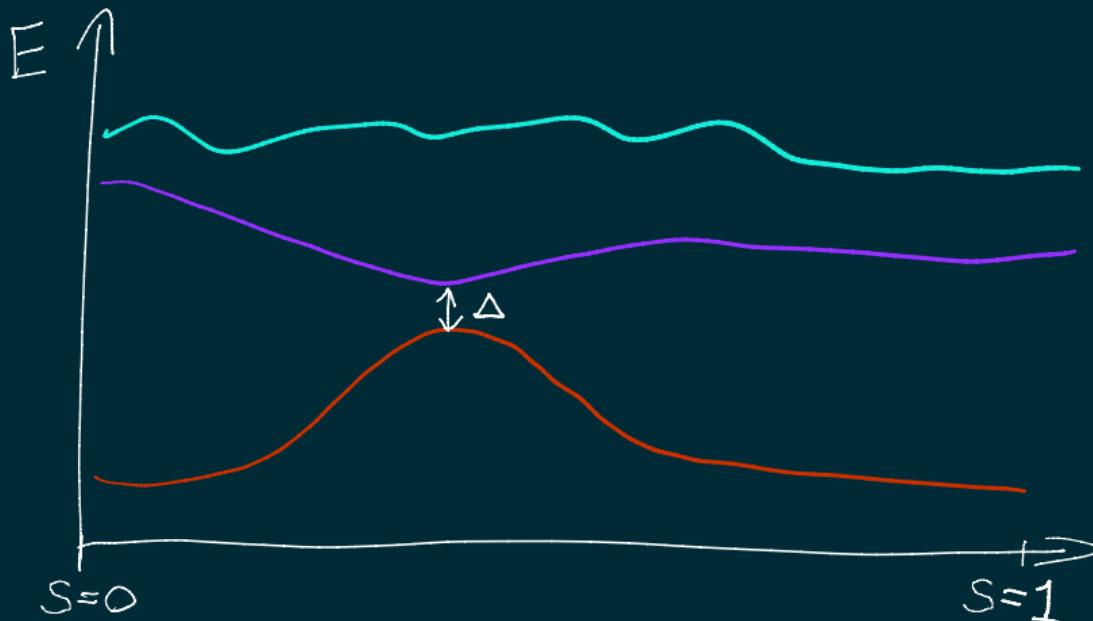
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- The ground state is accurately mapped if the evolution time is  $t = \Theta(1/\text{poly}(\Delta))$

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- ▶ Unfortunately, for hard problems the gap  $\Delta$  tends to become small
- ▶ An interesting special case is when the Hamiltonians have “no sign problem”,  
i.e., all off-diagonal matrix elements of  $H(s)$  are non-positive for every  $s \in [0, 1]$   
(note that this is a basis-dependent property)

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- ▶ However, there are topological obstruction to path integral Monte Carlo [Hastings & Freedman, 2013]
- ▶ Diffusion Monte Carlo is sensitive to  $\ell_1$  vs.  $\ell_2$  differences in the ground state [Jarret, Jordan, & Lackey, 2016]

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- ▶ In practice this issue can be often fixed by adding appropriate non-local moves

# Exponential quantum advantage with no sign problem

## Main result (informal)

There is a family of sparse sign-problem-free Hamiltonians on  $n$  qubits with a straight adiabatic path featuring a spectral gap  $\Delta = \Omega(1/\text{poly}(n))$ , whose evolution requires  $2^{\sqrt[5]{n}}$  queries to the Hamiltonian entries to simulate classically.

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## The corresponding graph problem (informal)

Given (via black-box access) a sparse graph on  $2^n$  vertices and a specific “ENTRANCE” vertex, we can find the “EXIT” vertex in  $\text{poly}(n)$  time via adiabatic evolution of a corresponding Hamiltonian which has  $1/\text{poly}(n)$  spectral gap and no sign problem. At the same time any classical randomized algorithm must make at least  $2^{\sqrt[5]{n}}$  queries to the graph (i.e., to the black-box) for finding the “EXIT”.

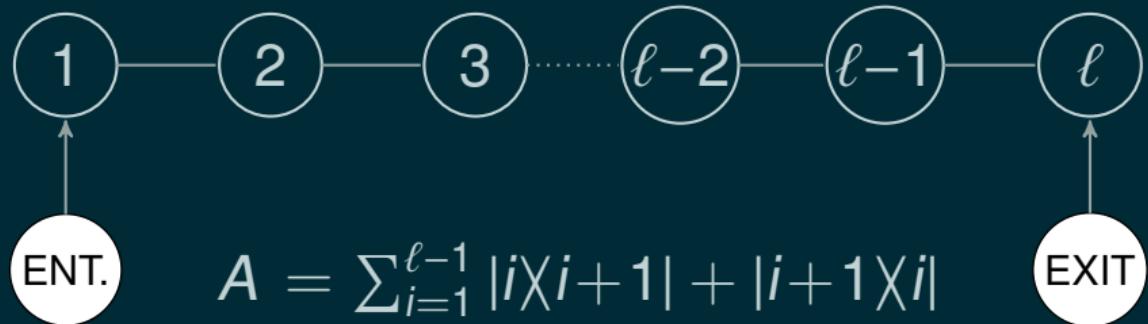
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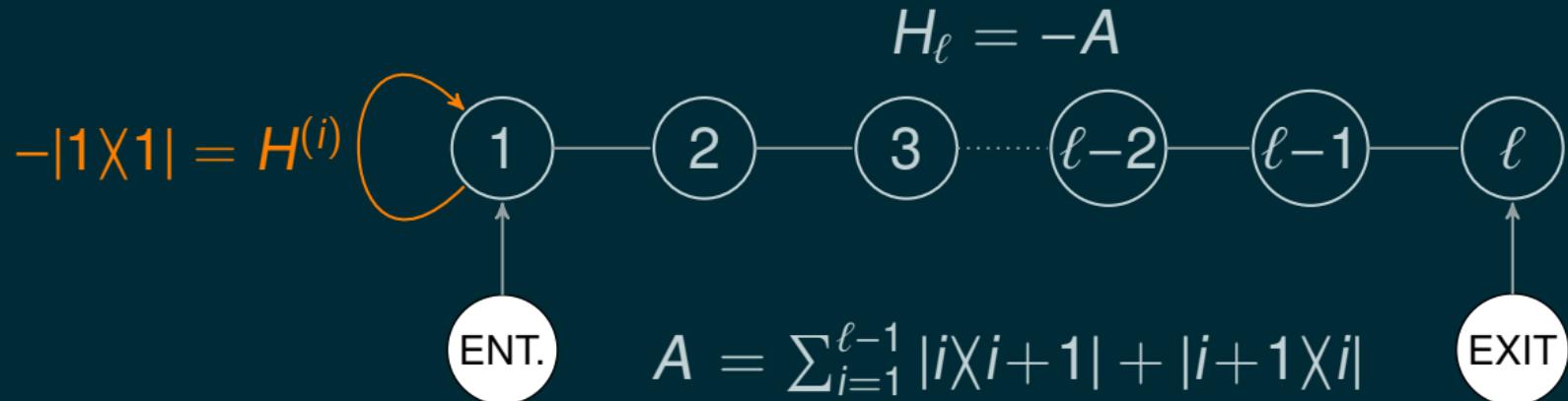


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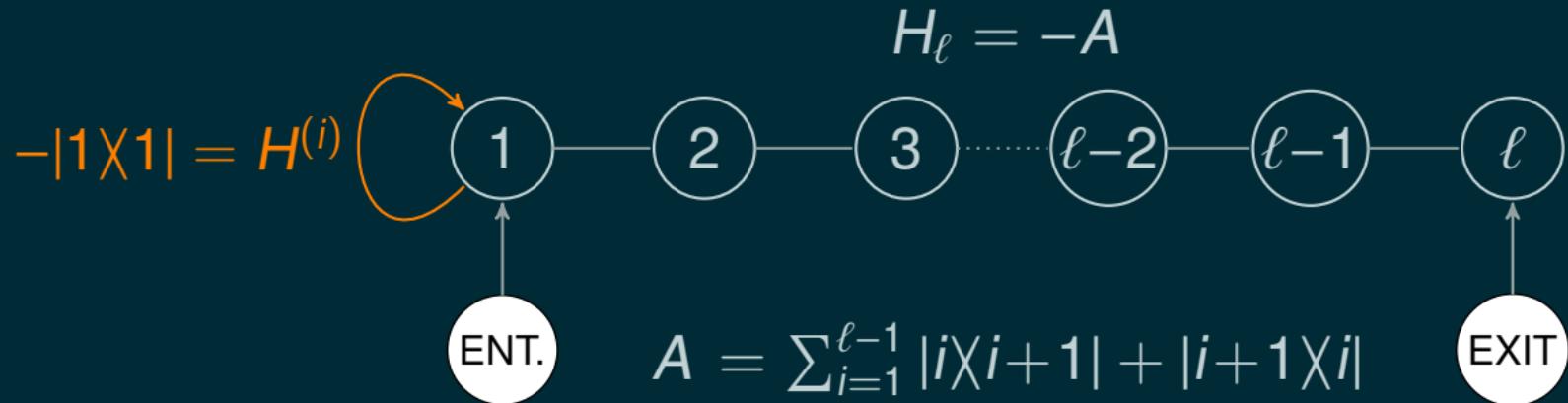
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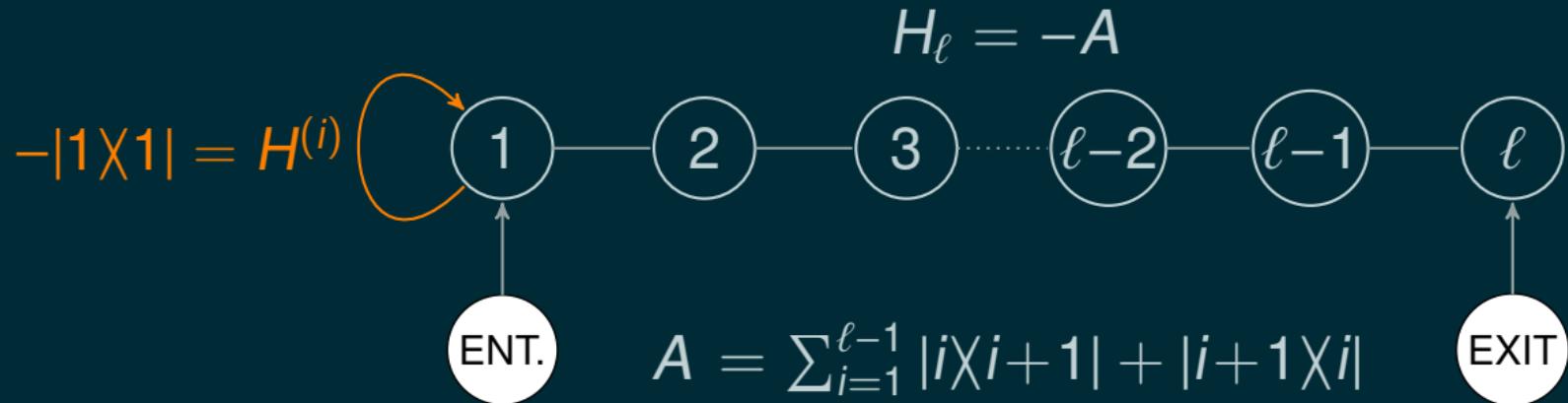


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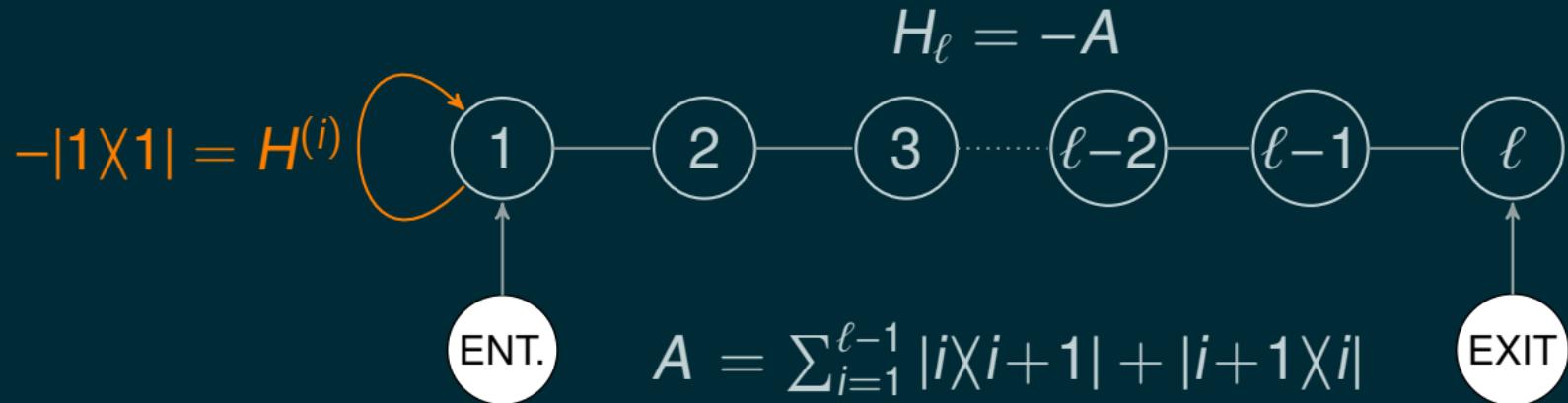
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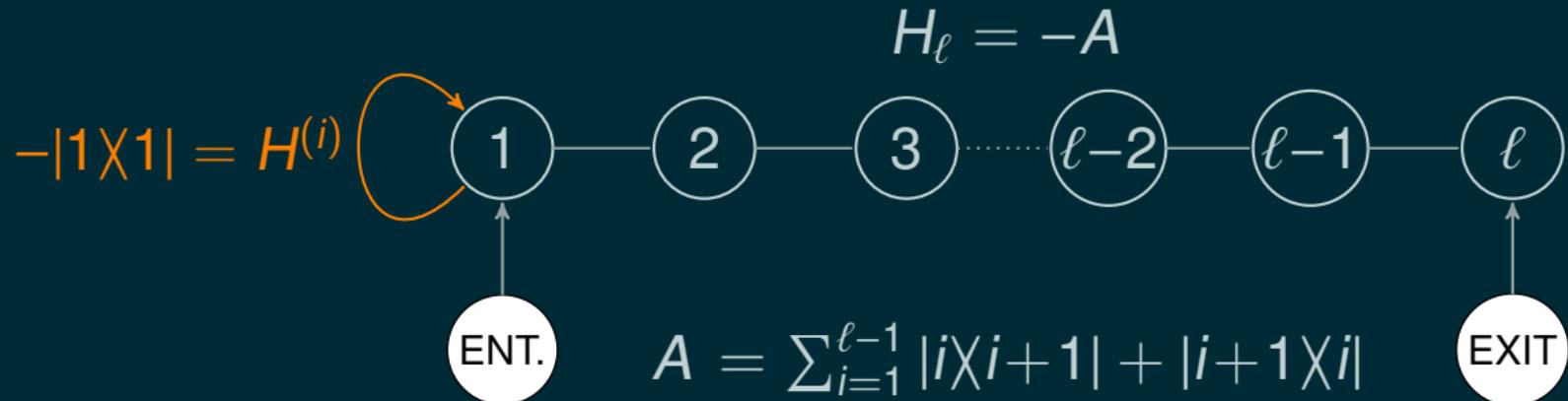


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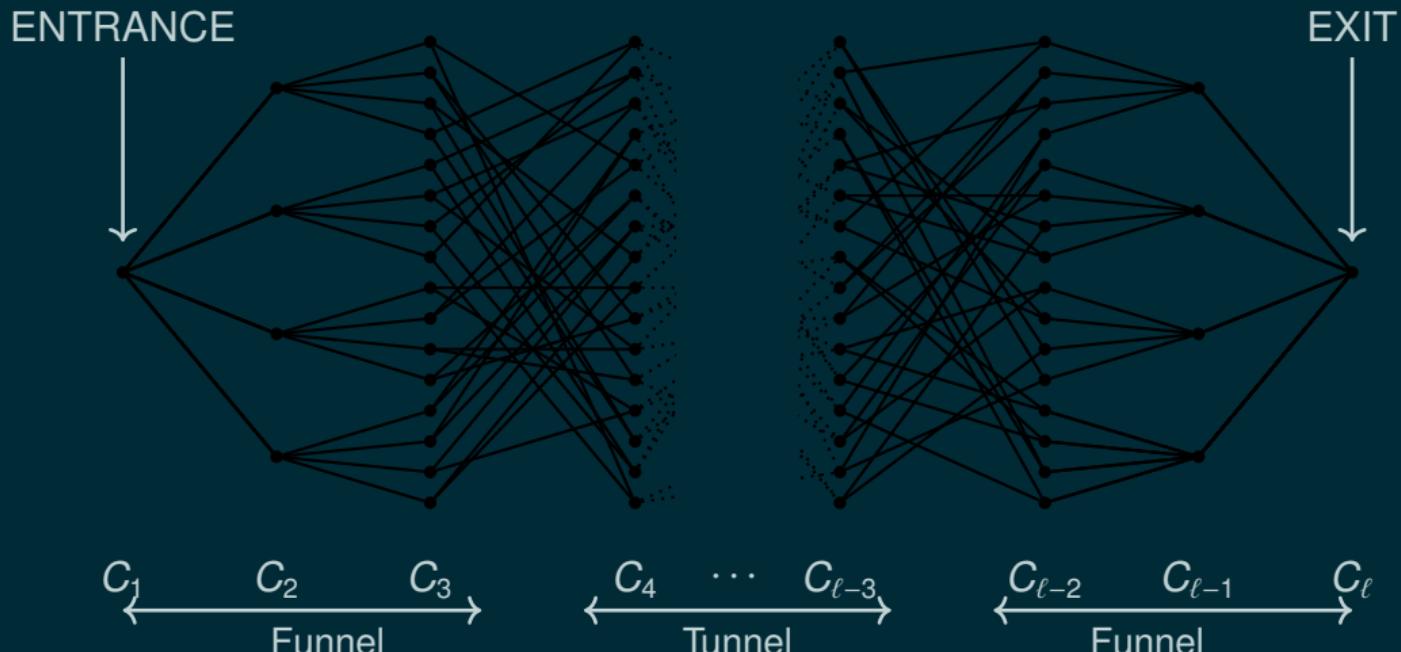


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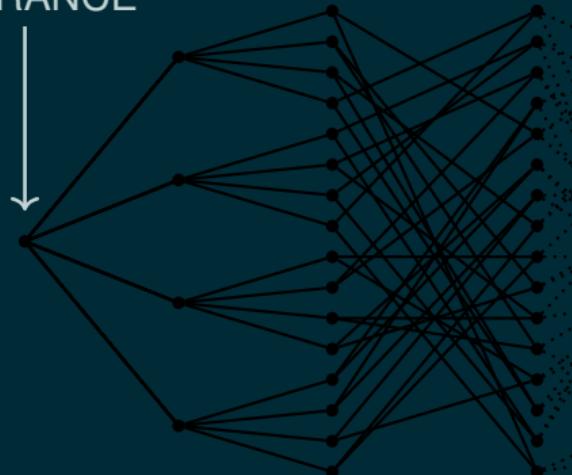
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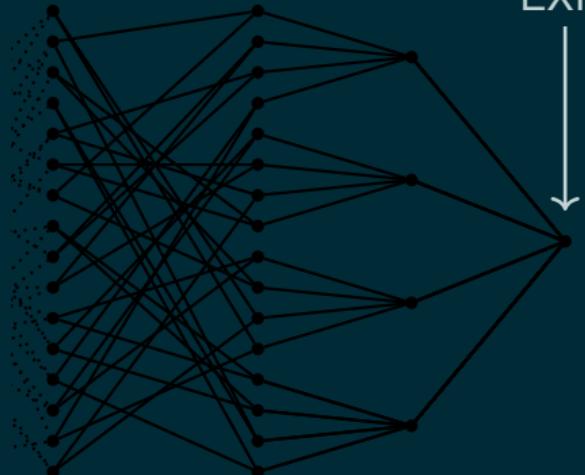


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EXIT



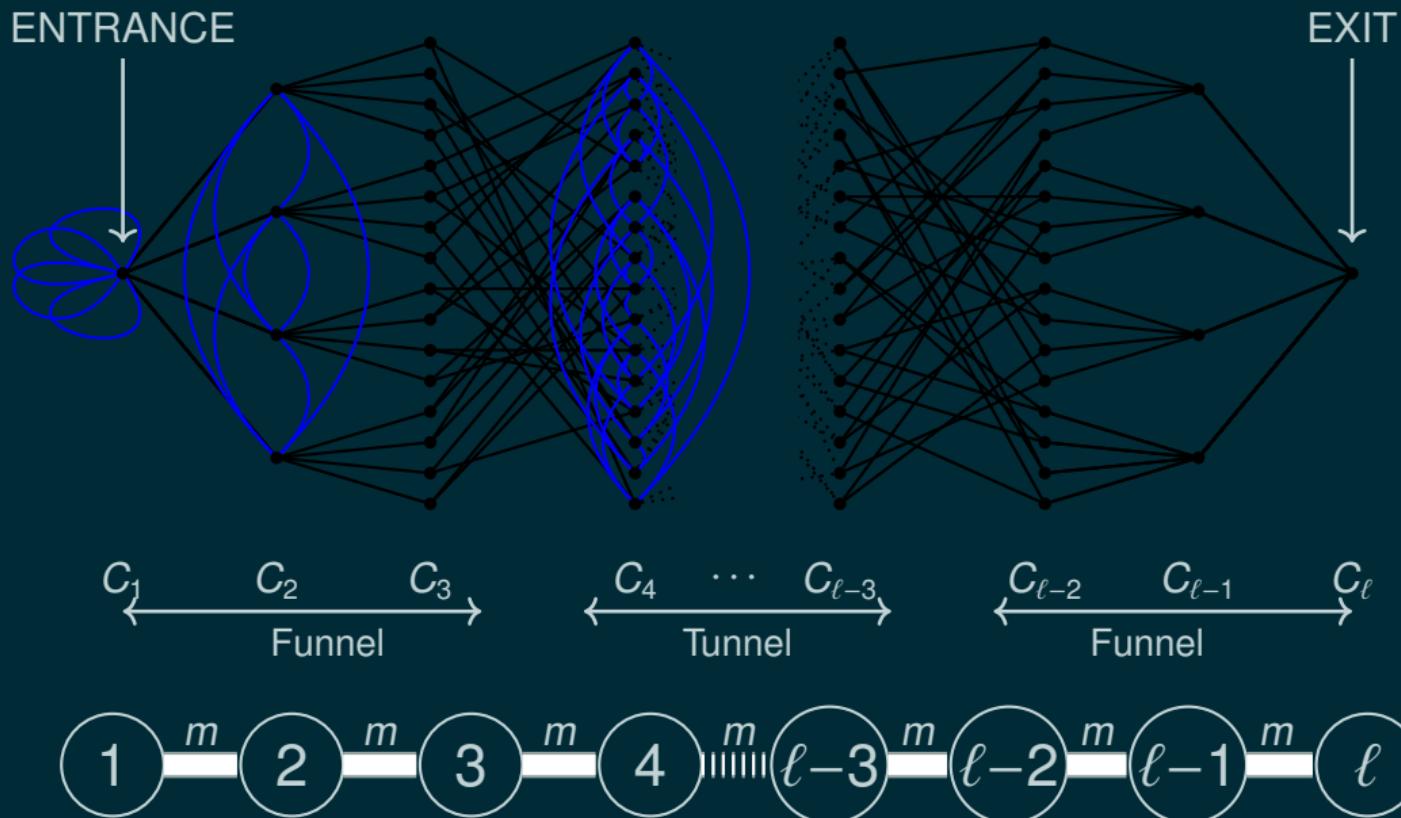
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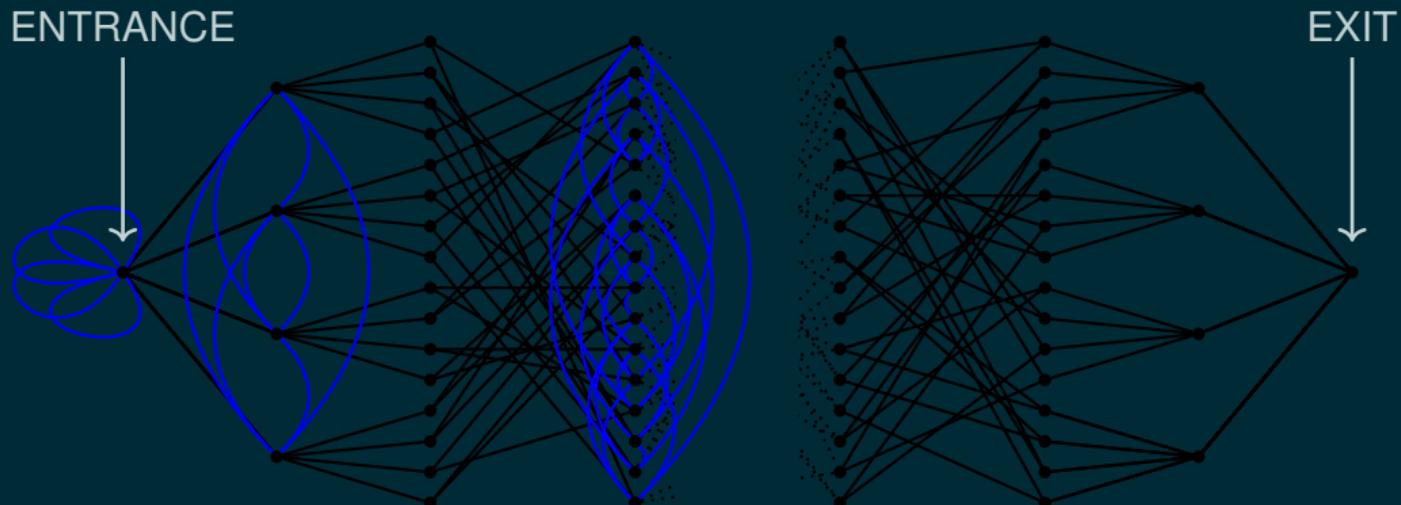
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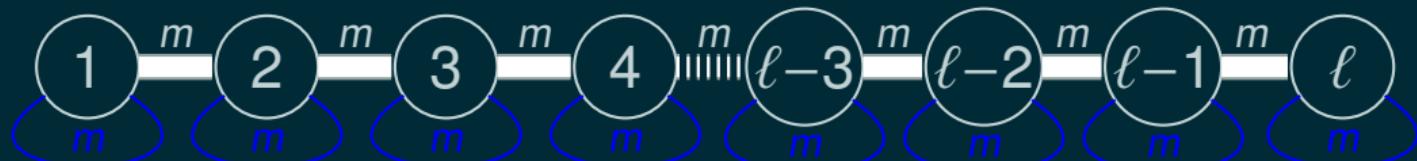
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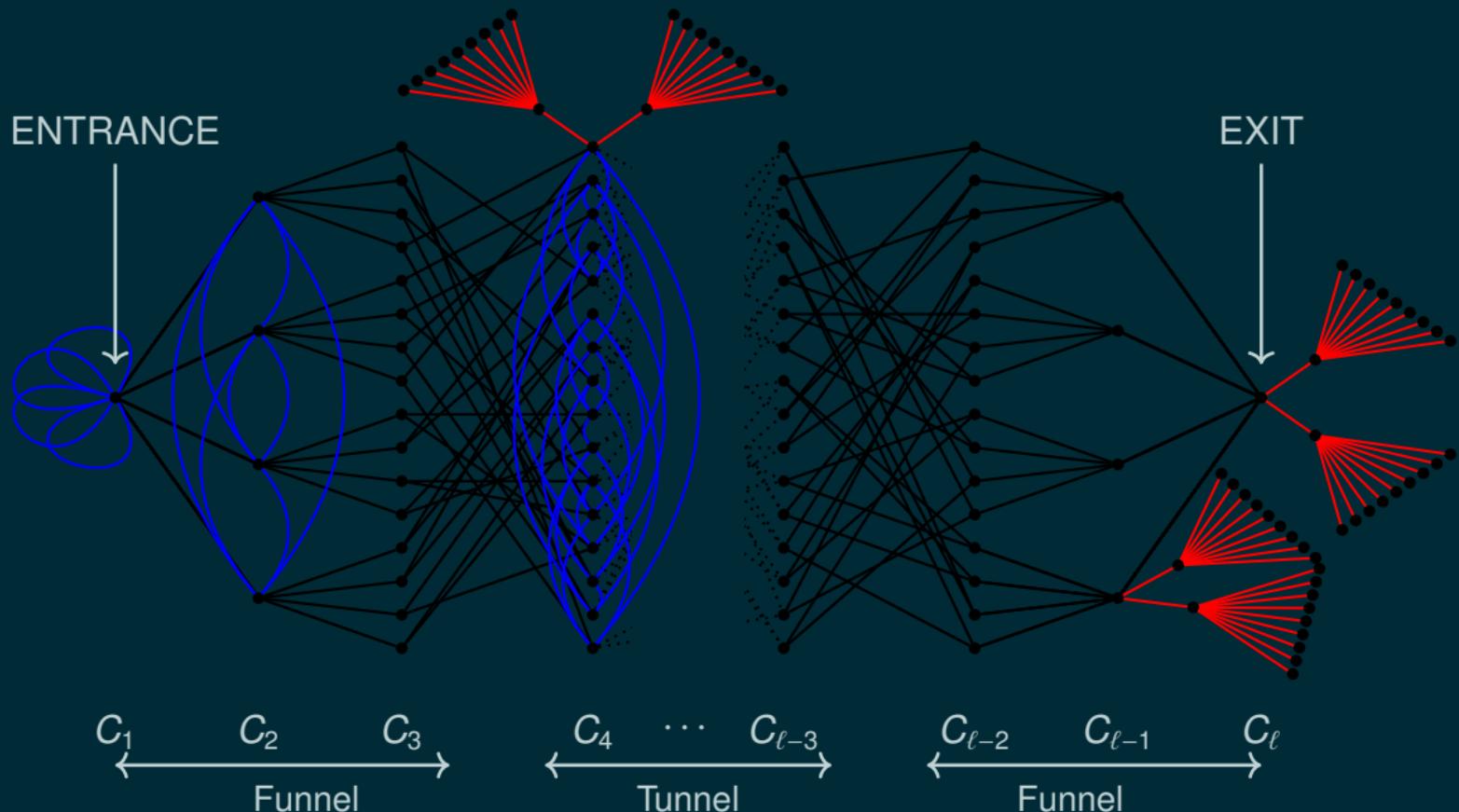
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- ▶ However, if the trees are  $\text{poly}(m)$  deep, then the  $\ell_1$  weight moves onto the trees!

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- ▶ The trees are designed such that the expected “hitting time” of leafs barely changes while moving deeper into a tree – making the “camouflage” trees very hard to recognize
- ▶ Due to the random labeling of vertices no classical algorithm can navigate the decorated graph, and any classical algorithm will “get lost” spending an exponential amount of time in the “camouflage forest” before finding the EXIT.

## Open questions

- ▶ Find a sign-problem-free Hamiltonian of practical interest providing a large speed-up!
- ▶ Are sign-problem-free Hamiltonians at least marginally easier in general? Is there a general simulation algorithm that works in time for example  $\sqrt{2^n}$ ?
- ▶ What is the classical complexity of simulating adiabatic evolution for frustrated local Hamiltonians with no sign problem? (See, e.g., [Bringewatt & Jarret, 2020].)